

The logo for VQEG, consisting of the letters 'VQEG' in a white, stylized font with a blue glow effect, set against a black rectangular background.

Predicting local distortions introduced by AV1 using Deep Features

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The logo for Netflix, featuring the word 'NETFLIX' in a bold, red, sans-serif font.The logo for Nantes Université, featuring a stylized 'U' icon followed by the text 'Nantes Université' in a black, sans-serif font.The logo for LS2N, featuring the letters 'LS2N' in a blue, stylized font with a decorative wave-like pattern below.

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The problem we are trying to answer

- Video encoding is driven by measures (SSE, SAD) to assess the visibility of distortion locally, but these **pixel-based measures** are not well tuned to how humans perceive distortions, but efficient to compute.

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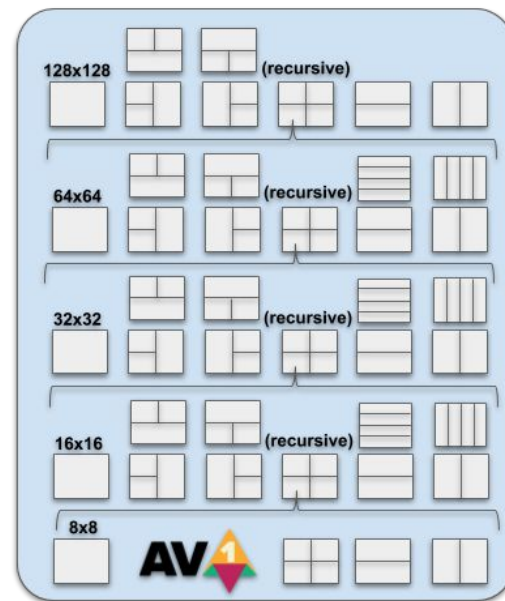
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- Our goal is to correct these measurements at a local horizon in a video to improve the overall quality and reduce bitrate usage: **What is this local horizon?**

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- Our goal is to correct these measurements at a local horizon in a video to improve the overall quality and reduce bitrate usage: **What is this local horizon?**
- Requirement: a ground truth dataset to drive the research development and metric creation. **What is this ground truth data? How can we leverage Deep Features extracted from Neural Network to correct SSE?**

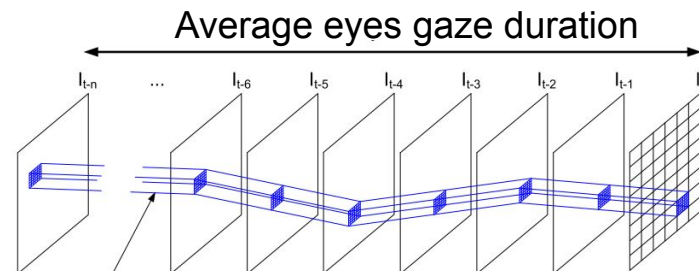
Connecting video encoding and localized Human Visual System perception with “Perceptual Unit”

- Video encoders make decisions on Coding Units (CUs): mode selection, partitioning, transform, filters ...



Connecting video encoding and localized Human Visual System perception with “Perceptual Unit”

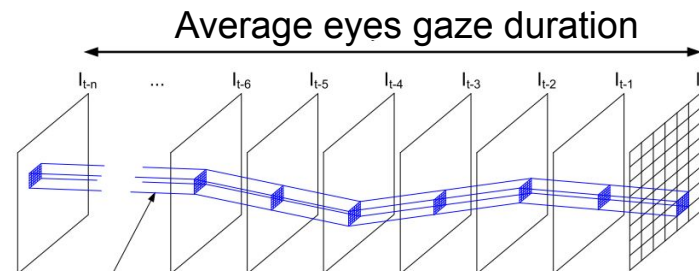
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 - **spatially located**, around foveated view: 1° of visual angle, 60ppd under standard viewing condition
 - **temporally located**: gaze fixation movement $\sim 200\text{ms}$
 - aligned along the direction of an object: **pursuit**



A spatio-temporal tube aligned along motion on multiple frames

Connecting video encoding and localized Human Visual System perception with “Perceptual Unit”

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- **Perceptual Unit (PU)**: same spatio-temporal horizon as a gaze on which we want to model how humans perceive distortion to drive CUs encoding



A spatio-temporal tube aligned along motion on multiple frames

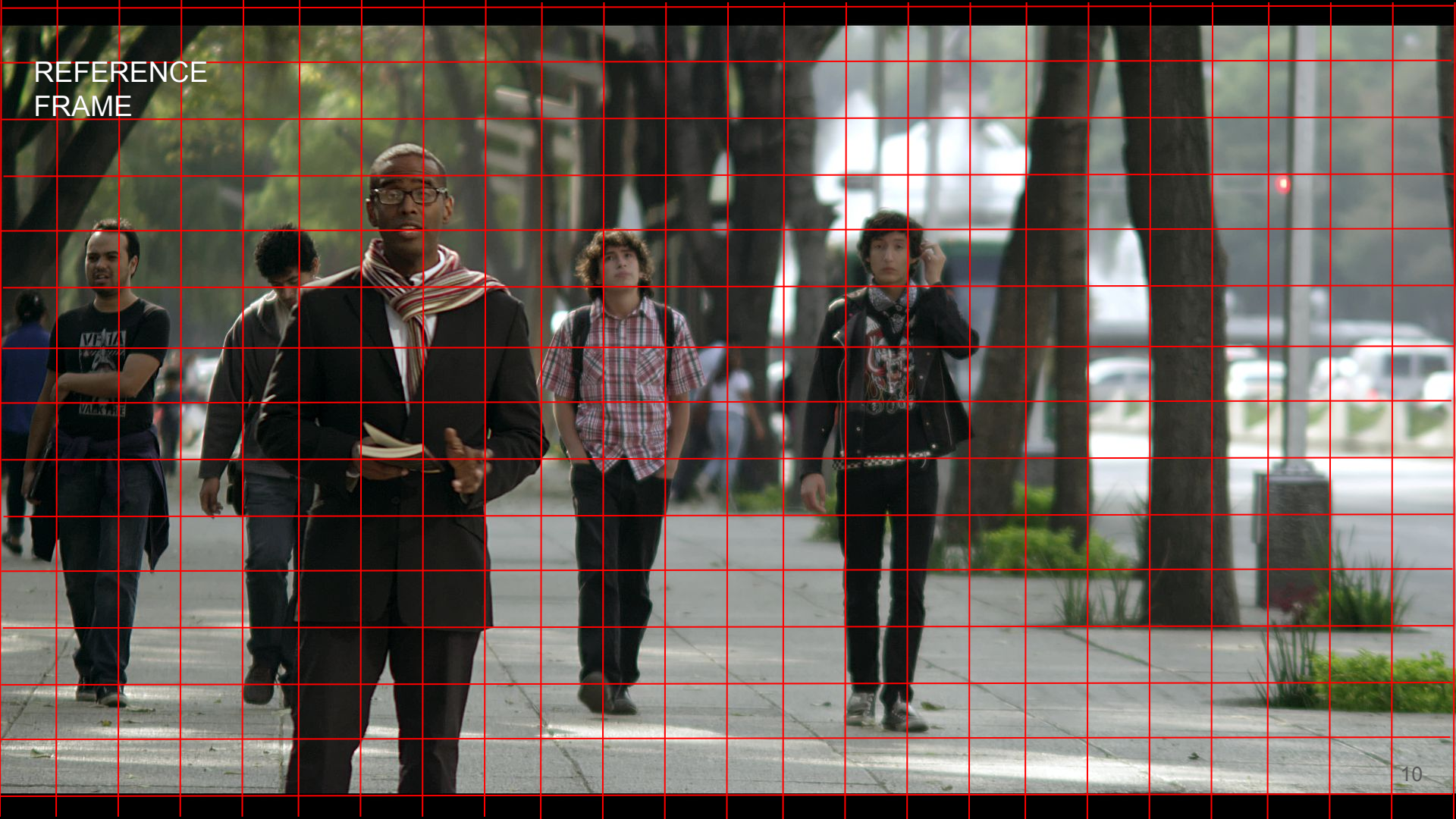
Visual example

Perceptual Units and Perceptual Difference curves in encoding process

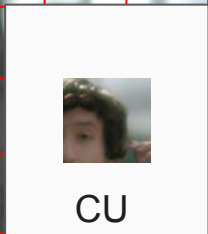
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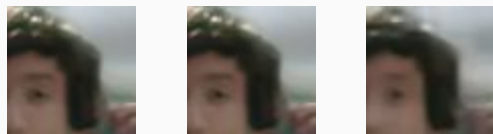
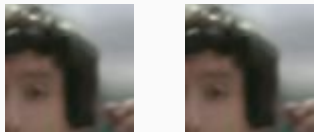
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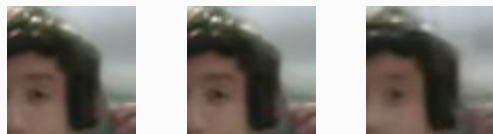
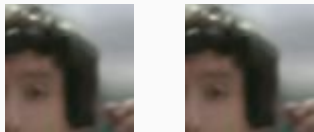


Candidates from encoder for CU



CU

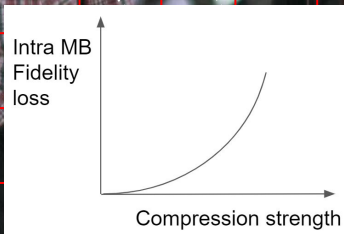
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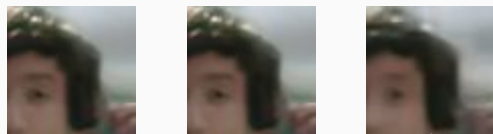
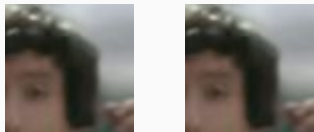
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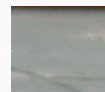
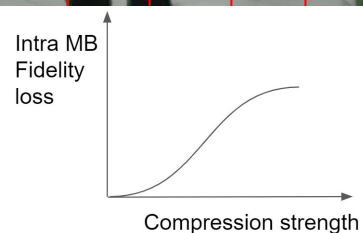
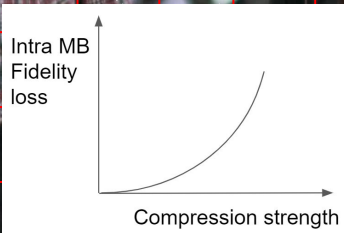
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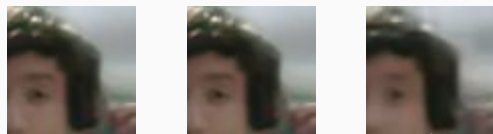
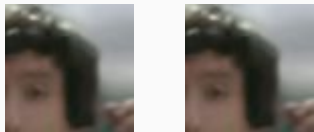


CU



another CU

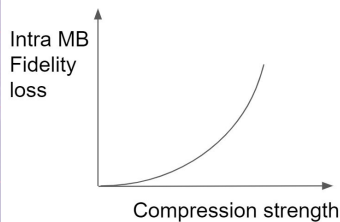
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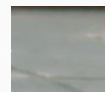
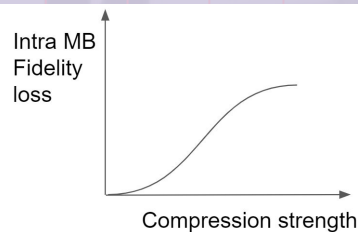
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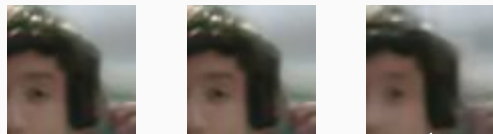
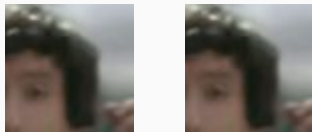


1. Intra scaling of Perceptual Difference curves



another CU

REFERENCE
FRAME

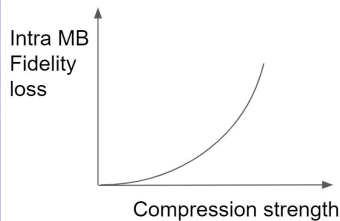
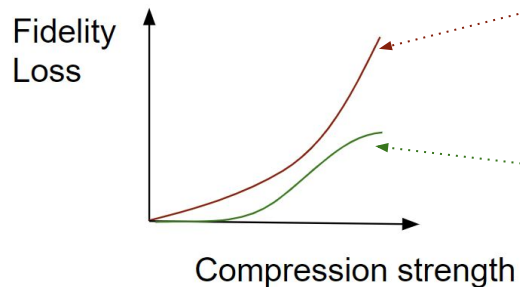


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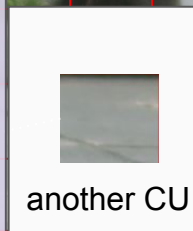
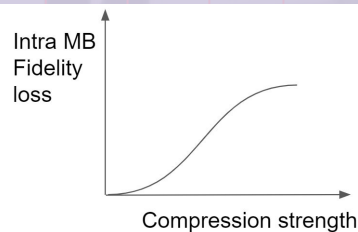


CU

2. Inter scaling of PD curves



1. Intra scaling of Perceptual Difference curves



another CU

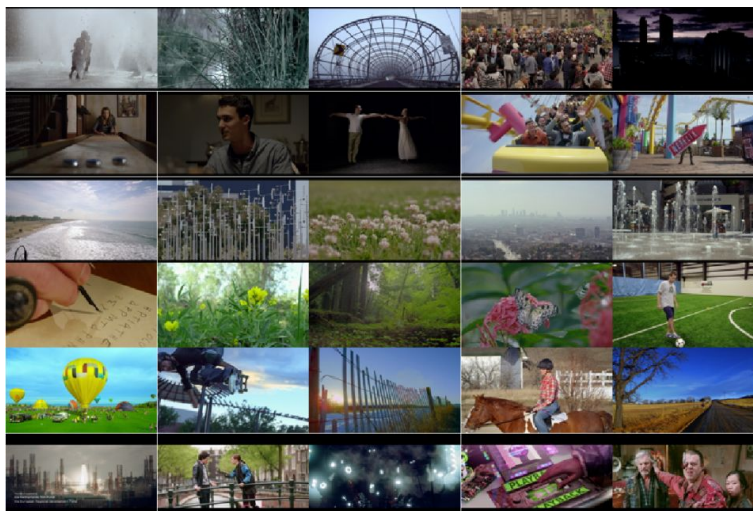
Dataset creation of tube-contents

Content selection and data collection

Content creation: encoding

To select tube-contents, we followed these steps:

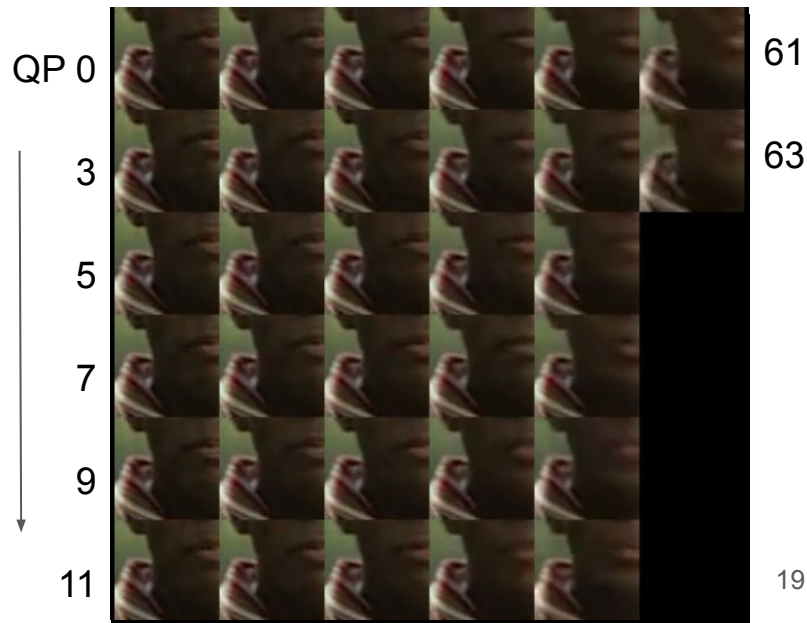
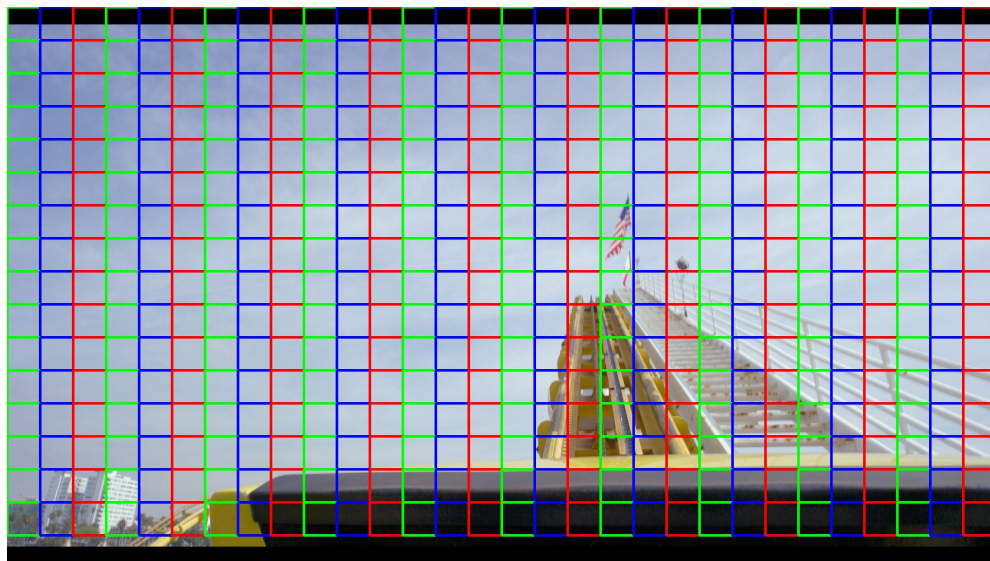
- **Step 1:** Encoding of sources (SRCs).
 - 115 SRCs from VideoSet dataset[1] @1080p 30fps
 - Encoding with libaom AV1 in Random Access mode at fixed QP
 - 31 Processed Video Sequences (PVS): encoded with --cq-level ranging from 3 to 63, step of 2



Content creation: tube-content extraction

To select tube-contents, we followed these steps:

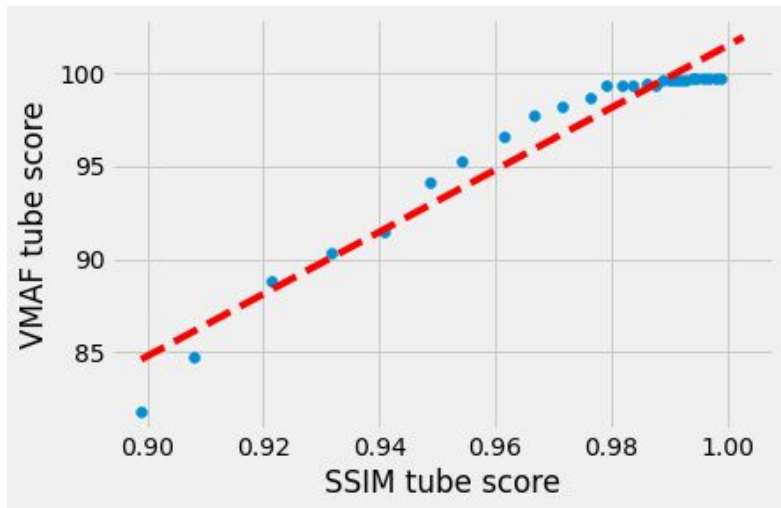
- **Step 2:** Extraction of **tube-contents** aligned on the motion: tube size = a PU (64x64px, 400ms)
 - A tube-content: a reference tube and 31 distorted version of it from PVS
 - 100K tube-contents extracted from the 115 SRCs



Clustering of tube-contents

To select tube-contents, we followed these steps:

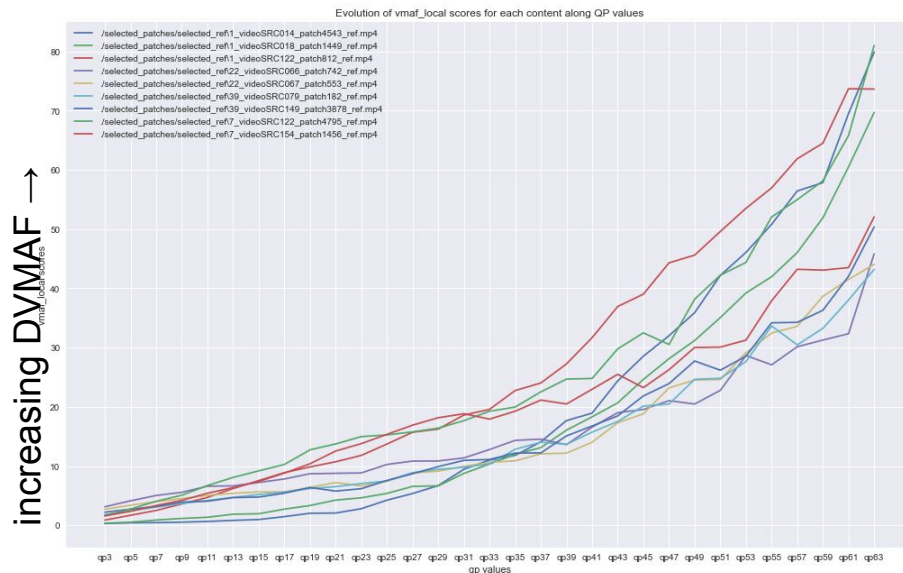
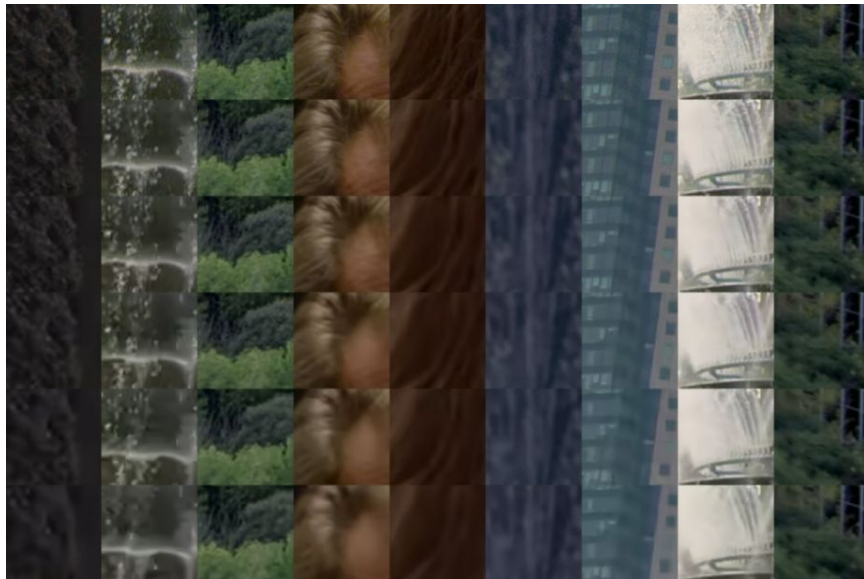
- **Step 3:** Clustering of the 100K tube-contents from the response of quality metrics.
 - Quality metrics used: VMAF, SSIM, PSNR, LPIPS
 - Feature extraction from the relation (**red line**) in all pairs of quality metrics (slope, intercept, error)
 - 96 clusters are learned with K-Means



Tube-contents selection for subjective evaluation

To select tube-contents, we followed these steps:

- **Final step:** 268 tube-contents (2+ per cluster) sampled.
 - Per tube-content: 6 distortion levels out of the 31 available are selected using VMAF
 - VMAF as a fidelity proxy for distortion level spacing selection ($DVMAF = 100 - VMAF$)

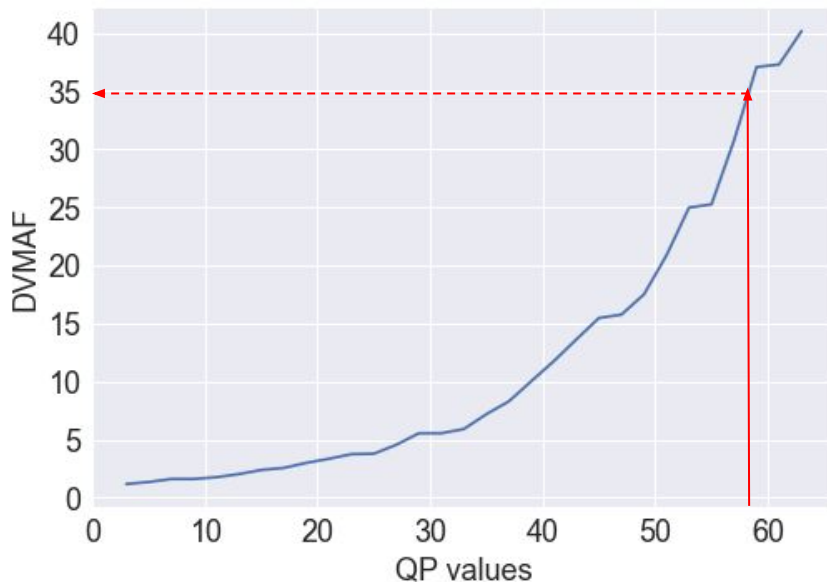


increasing QPs values →

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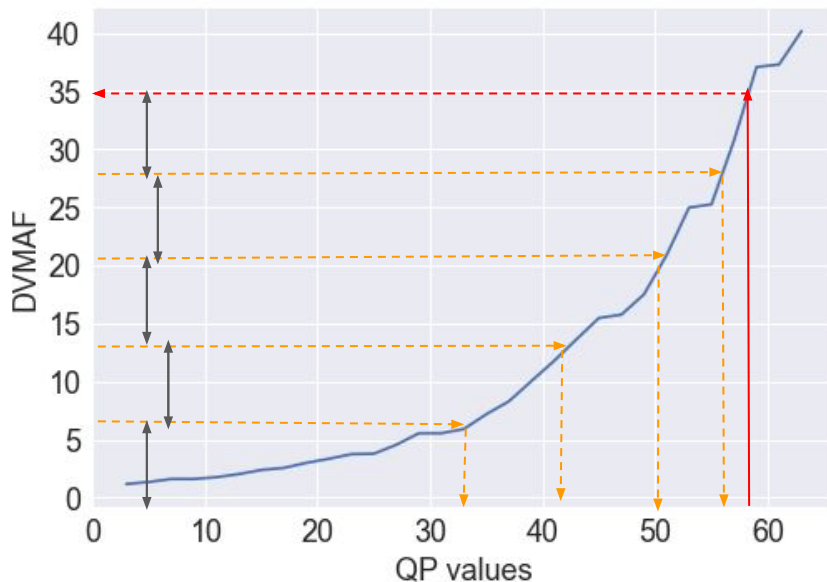
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Example of tube-contents and distortion levels?

What kind of subjective data are we trying to collect on a PU?

A fidelity loss evaluation: How much distortions the human eyes can perceive between a reference PU and an encoded/compressed/distorted version of it?



Not noticeable distortion ($d = 0$)



Noticeable distortion ($d > 0$)

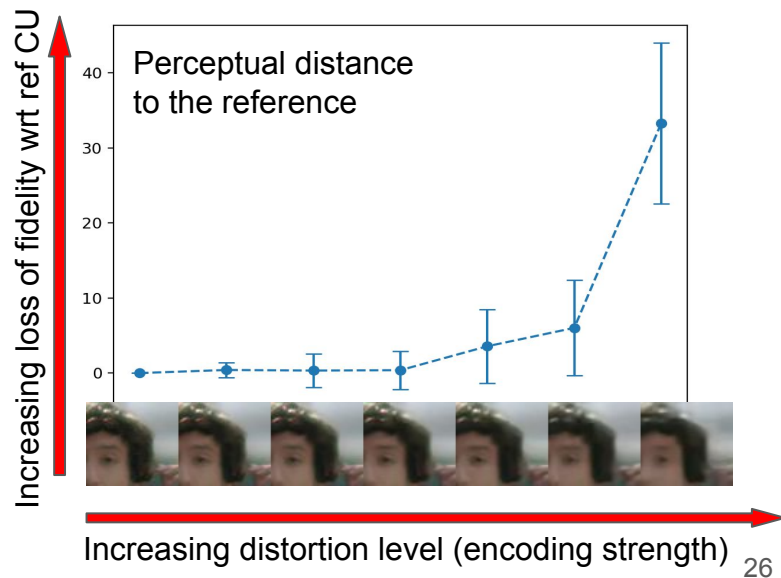
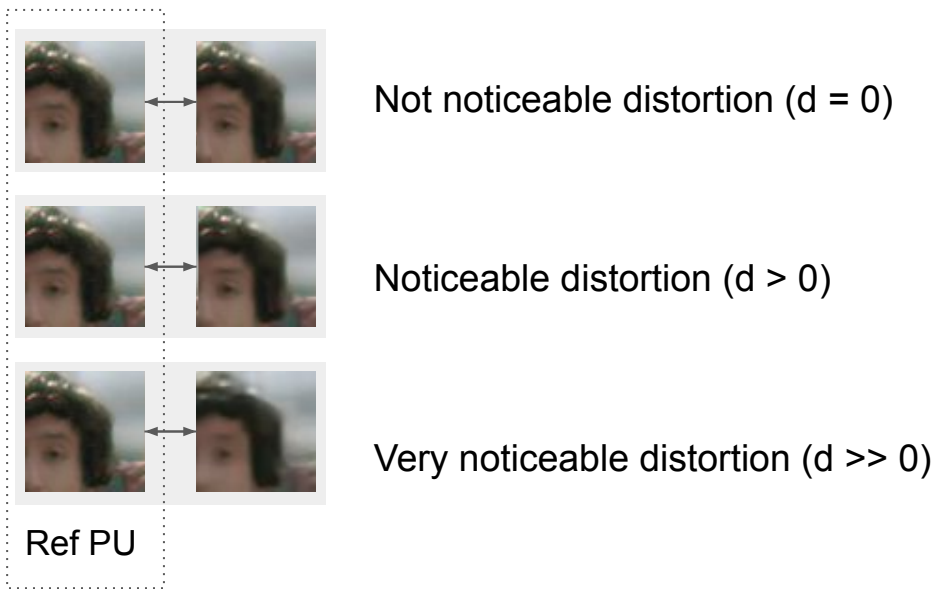


Very noticeable distortion ($d \gg 0$)

Ref PU

What kind of subjective data are we trying to collect on a PU?

A fidelity loss evaluation: How much distortions the human eyes can perceive between a reference PU and an encoded/compressed/distorted version of it?



Collecting Ground Truth Efficiently

- Available subjective methodologies:
 - Pairwise comparison, (with boosting strategies as ARD, Hybrid-MST[1], ASAP[2] ...)
 - **Quadruplets, triplets, 2-AFC, ... with boosting strategies AFAD[3]**
- From subjective judgments to perceptual continuum:
 - Bradley-Terry, Thurstonian models, ...
 - **Maximum Likelihood Difference Scaling MLDS[4] solvers**

[1] Li, J., Mantiuk, R., Wang, J., Ling, S., & Le Callet, P. (2018). Hybrid-MST: A hybrid active sampling strategy for pairwise preference aggregation. *Advances in neural information processing systems*, 31.

[2] Mikhailiuk, A., Wilmot, C., Perez-Ortiz, M., Yue, D., & Mantiuk, R. K. (2021, January). Active sampling for pairwise comparisons via approximate message passing and information gain maximization. In *2020 25th International Conference on Pattern Recognition (ICPR)* (pp. 2559-2566). IEEE.

[3] A. Pastor, L. Krasula, X. Zhu, Z. Li and P. Le Callet, "Improving Maximum Likelihood Difference Scaling Method To Measure Inter Content Scale, 2022 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), pp. 2045-2049, doi: 10.1109/ICASSP43922.2022.9746681.

[4] Knoblauch, K., & Maloney, L. T. (2008). MLDS: Maximum likelihood difference scaling in R. *Journal of Statistical Software*, 25, 1-26.

Quadruplet “intra” and “inter-content” comparison

- Participants perform subjective annotations on “intra” and “inter-content” quadruplets
- 50 000 judgments collected, 25 000 “intra” and 25 000 “inter” from naïves observers
- Experiment in crowdsourcing and observers annotated 40 quadruplets per session (~7min)

“INTRA”

Where do you perceive a greater difference between the lower two and the upper two patches?



“INTER”

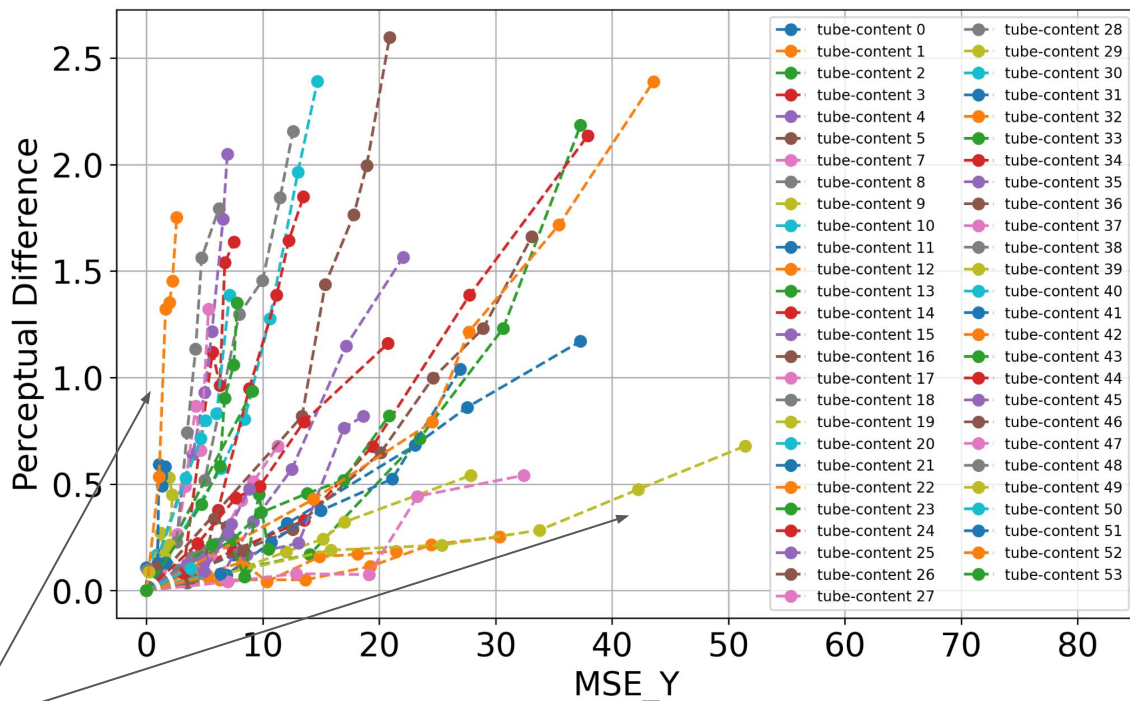
Where do you perceive a greater difference between the lower two and the upper two patches?



Example of PD–MSE curves obtained

Here, the 54 PD–MSE curves in the test set of dataset (20%):

- MSE distortion on X-axis
- subjective perceptual difference from observers on Y-axis

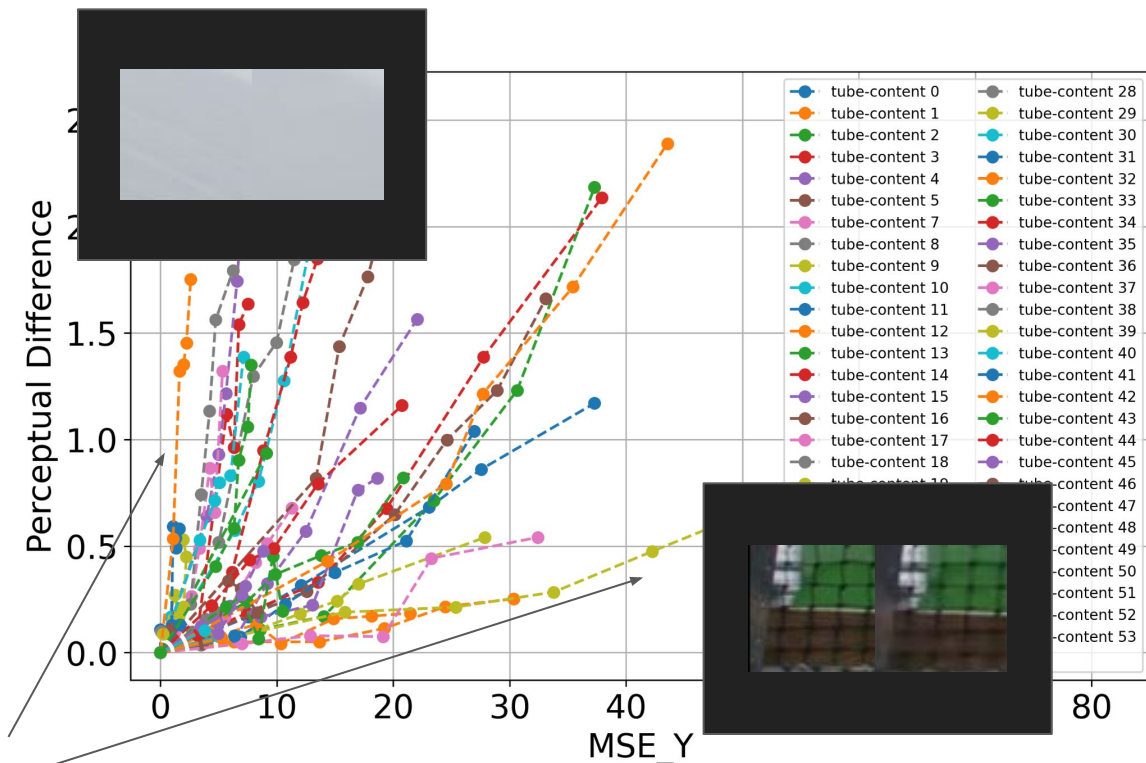


Example of under and over estimated distortions if we use MSE_Y as a PD predictor

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Example of under and over estimated distortions if we use MSE_Y as a PD predictor

Per tube weighting of MSE from Deep Semantic Features

PD-curve modelisation, proposed model, training and performances

proposed model for PD–MSE curve prediction

- step 0: model PD–MSE curves
- step 1: extract deep learning features from references tubes
- step 2: perform dimensionality reduction with PCA
- step 3: use SVM from topK PCA features pooling and predict PD-curves slopes

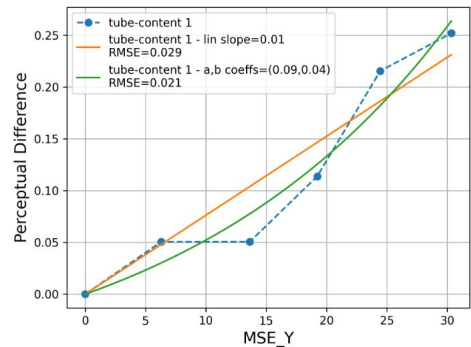
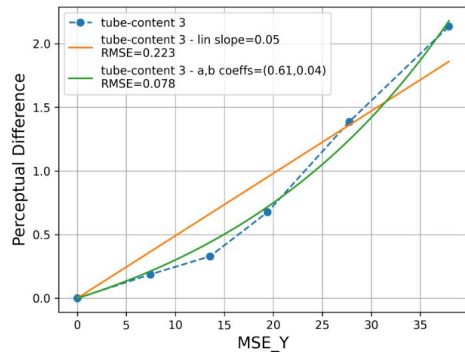
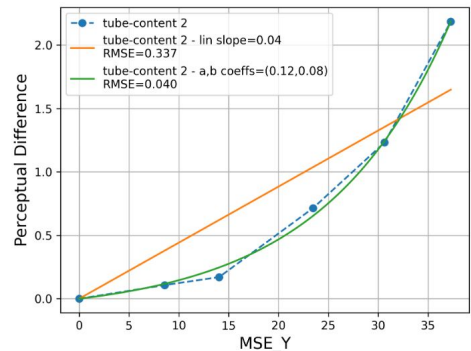
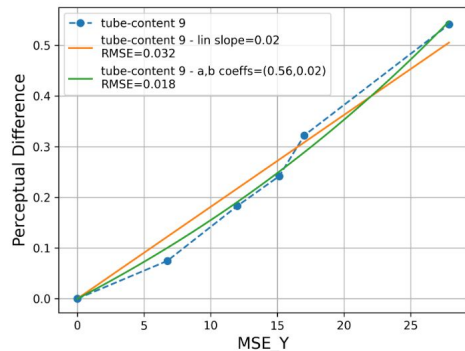
Step 0: modeling of PD–MSE curves

Use prior knowledge to simplify and model PD–MSE curves with linear function (orange) or exp function (green)

$$PD'_{score} = A \times MSE_Y$$

$$PD'_{score} = A \times (e^{B \times MSE_Y} - 1)$$

Train models to predict linA, and expA + expB



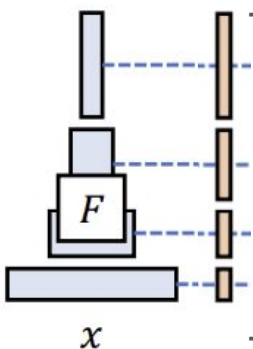
Step 1: extract Deep Learning features from reference tubes

- Why extract DL features from reference tubes only?
 - as we aim to correct MSE, a cheap statistic available during encoding

- Process for each reference tube:

- pass each frame patch in Neural Network backbone (AlexNet, VGG, ...)
- get each layer filter activation
- average them along spatial dimension
- then compute temporal average and temporal std
- obtain finally 2 vectors of 1152 features (AlexNet) per reference tube

- Perform the operation over the 100K tubes of the database

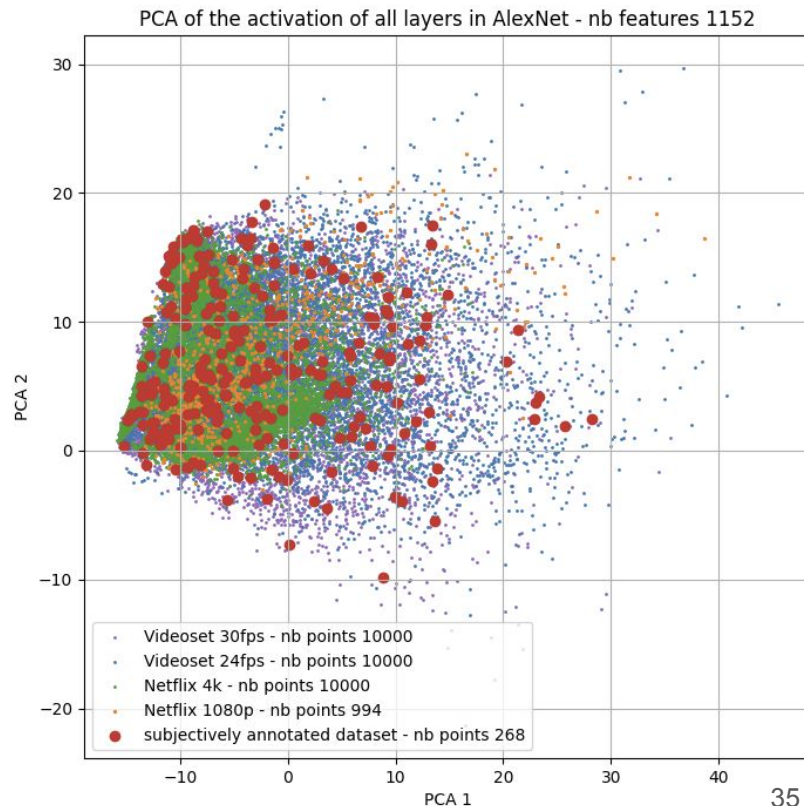


Step 2: perform dimensionality reduction with PCA

Goal: reduce 1152 features vectors to K features to ease model training on limited data

Use PCA to learn a projection from extracted features from 100K unlabeled tube-contents

Use the learned projection to extract top K Principal Components of train set features



Training options

$$mse_{i,j} = MSE(Tube_{i,0}, Tube_{i,j}) = MSE(Tube_{i,ref}, Tube_{i,j})$$

Learn SVM pooling to predict a subjective score for content i , distortion j :

$$PD_{i,j} = SVM(pca_i^1, pca_i^2, \dots, mse_{i,j})$$

Learn SVM pooling to predict slope of linear fitting

$$Slope_i = SVM(pca_i^1, pca_i^2, \dots)$$

$$PD_{i,j} = Slope_i \times mse_{i,j}$$

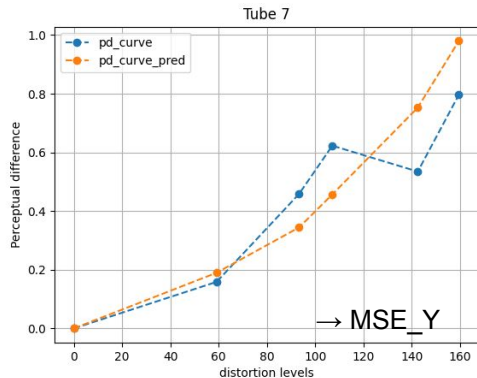
Learn 2 SVMs to predict a, b coeff of exp fitting:

$$a_i = SVM_a(pca_i^1, pca_i^2, \dots)$$

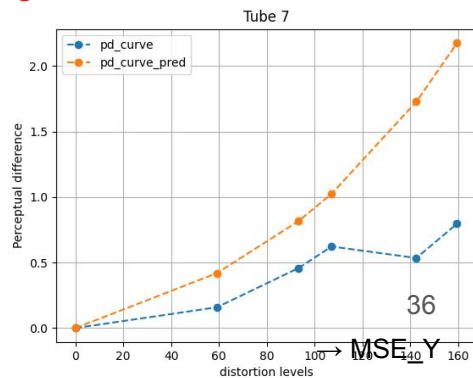
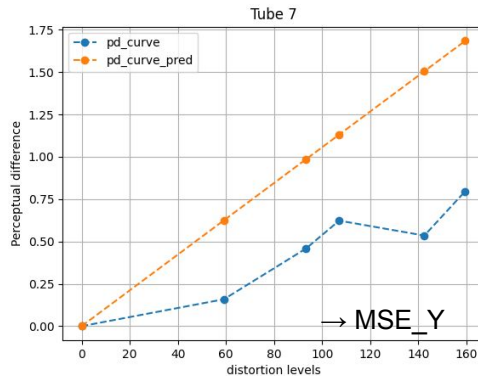
$$b_i = SVM_b(pca_i^1, pca_i^2, \dots)$$

$$PD_{i,j} = a_i \times (e^{b \times mse_{i,j}} - 1)$$

No constraint



Add our prior knowledge



Performance of all metrics on test set

Comparison with Full Reference metric (classic and Deep Learning based) and “Reference-only/MSE corrector” metrics

Prior modeling of the PD–MSE curves increases performances

TABLE II
FULL-REFERENCE AND REFERENCE-ONLY METRICS SCORES ON DATASET TEST SET. * INDICATE PERFORMANCES OF RETRAINED METRICS.

Type	Metrics	PLCC	SRCC	KRCC	RMSE
Full-Reference IQA/VQA no semantic	PSNR _{CB}	0.472	0.594	0.428	0.535
	PSNR _{CR}	0.447	0.539	0.376	0.539
	PSNR _Y	0.517	0.685	0.507	0.526
	SSIM [4]	0.629	0.763	0.586	0.481
	VIF [22]	0.693	0.780	0.603	0.431
	DLM [23]	0.846	0.869	0.696	0.321
	VMAF [8]	0.833	0.867	0.694	0.335
	VMAF*	0.875	0.900	0.747	0.291
DL Full-Reference IQA semantic	LPIPS-vgg [1]	0.711	0.795	0.631	0.420
	LPIPS-squeeze	0.674	0.785	0.622	0.445
	LPIPS-alex	0.628	0.754	0.588	0.470
	DISTS [3]	0.787	0.851	0.671	0.369
Reference-Only no semantic	WPSNR [5]	0.618	0.819	0.642	0.483
	XPSNR [6]	0.665	0.828	0.652	0.461
	libaom tune=ssim	0.653	0.795	0.614	0.476
DL Reference-Only VQA	our model (raw)	0.844	0.878	0.714	0.336
	our model (lin)	0.843	0.888	0.721	0.328
	our model (exp)	0.852	0.888	0.728	0.316

Conclusion

- Human perception is important to drive encoding algorithms (AV1, ...)
- Creation of a dataset of 268 tube-contents with inter-content scaling
- Benchmark of existing quality metrics
- Creation of a metric to correct MSE
- Ongoing next steps:
 - Perceptually tuned Rate Distortion Optimization in libaom
 - going from local to global video scale distortion prediction