

# Toward Behavioural Analysis of 6-DoF User When Consuming Immersive Media

---

**Silvia Rossi**, Irene Viola,  
Laura Toni and Pablo Cesar

- Introduction
- User navigation in 3- vs. 6-DoF environment
- User Trajectory Analysis in 6-DoF
- Results
- Conclusion

# Traditional media consumption

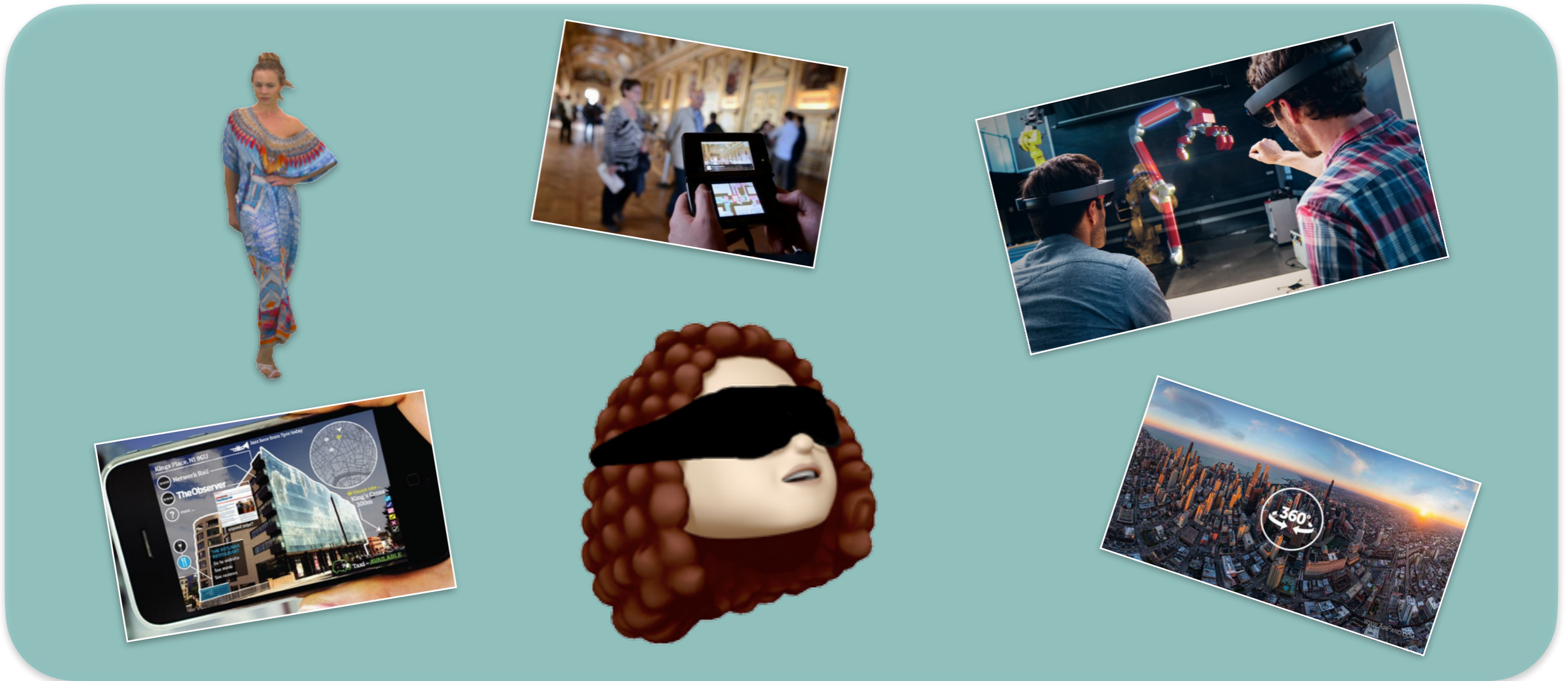


# VR: a user-centric era

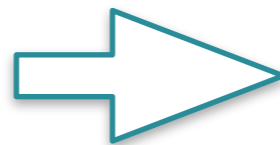




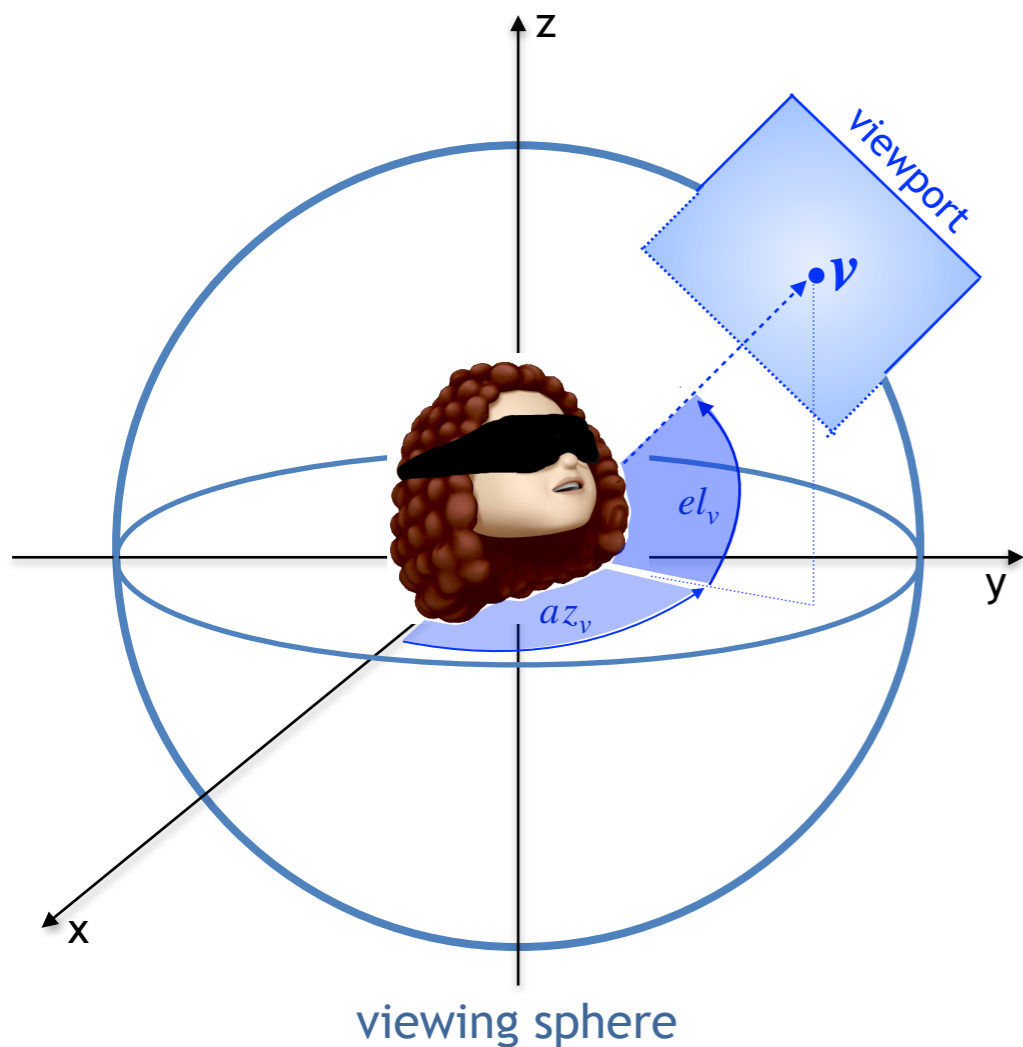
# VR: a user-centric era



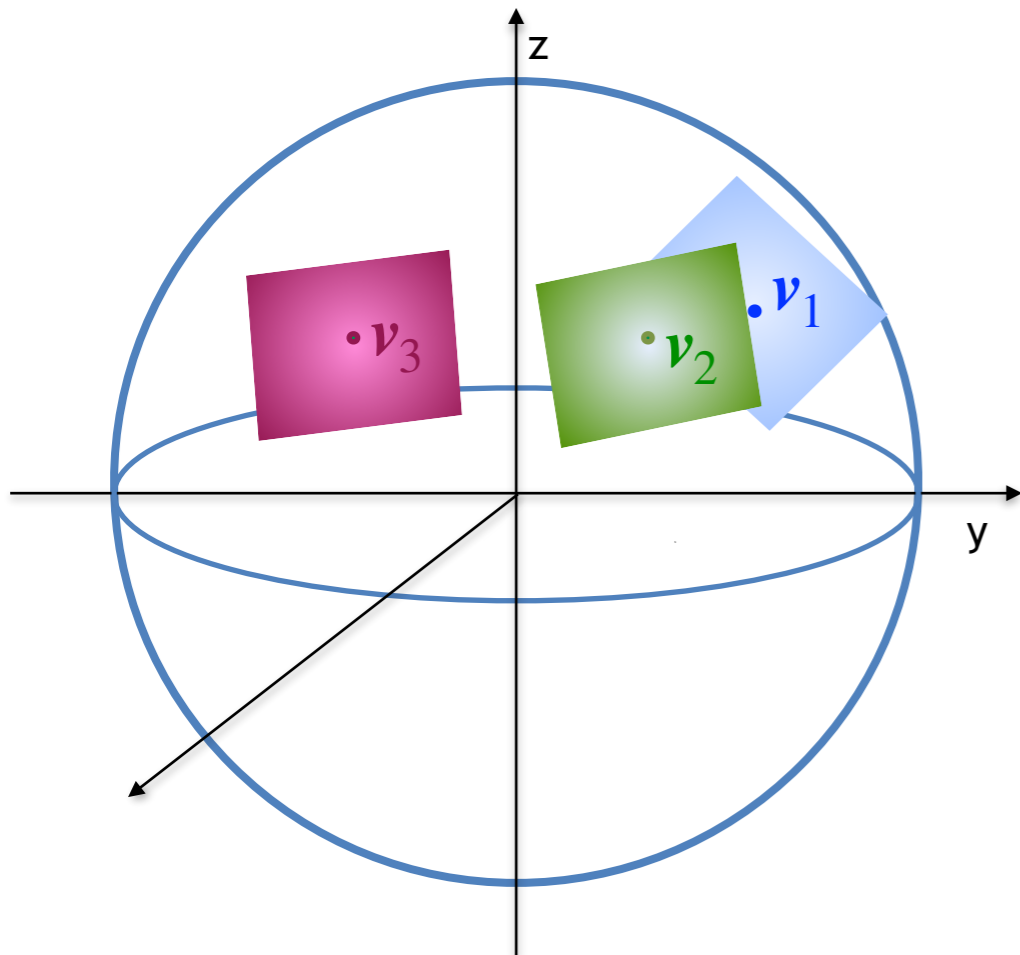
High Quality



Need of understanding  
user behaviour



- Omnidirectional video is the de-facto VR format
- The user is virtually positioned at the center of the sphere
- The head is the only “interface” for interactivity
- The media is displayed from an *inward* position



Distance between **viewport centres** as proxy of viewport overlap [1]



Distance as metric to assess user similarity

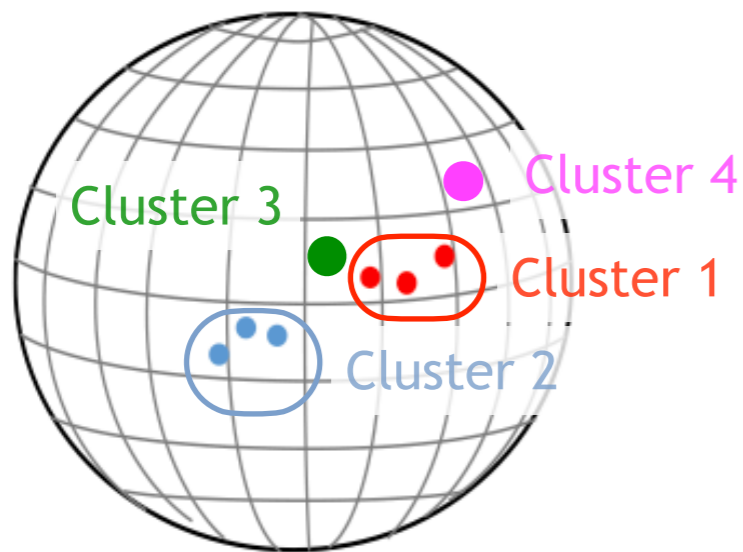


Clique-based clustering to detect user with similar behaviour



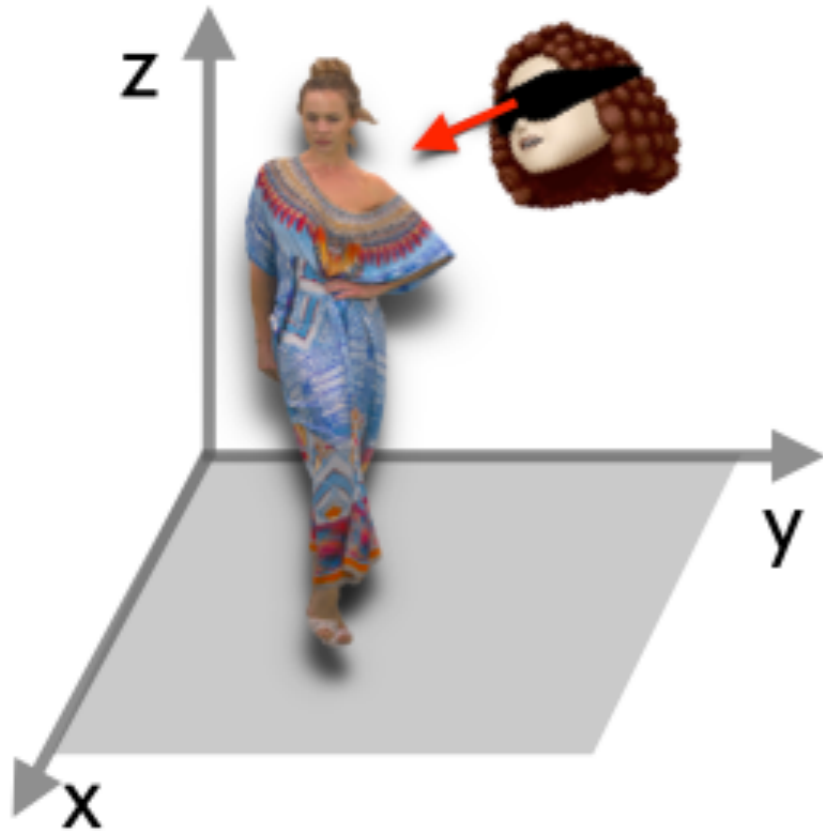
The position of viewport center over time is highly informative to identify user behaviour.

A **clique-based clustering** has been proposed in [1] to identify similar users that are attending the same portion of the omnidirectional content.



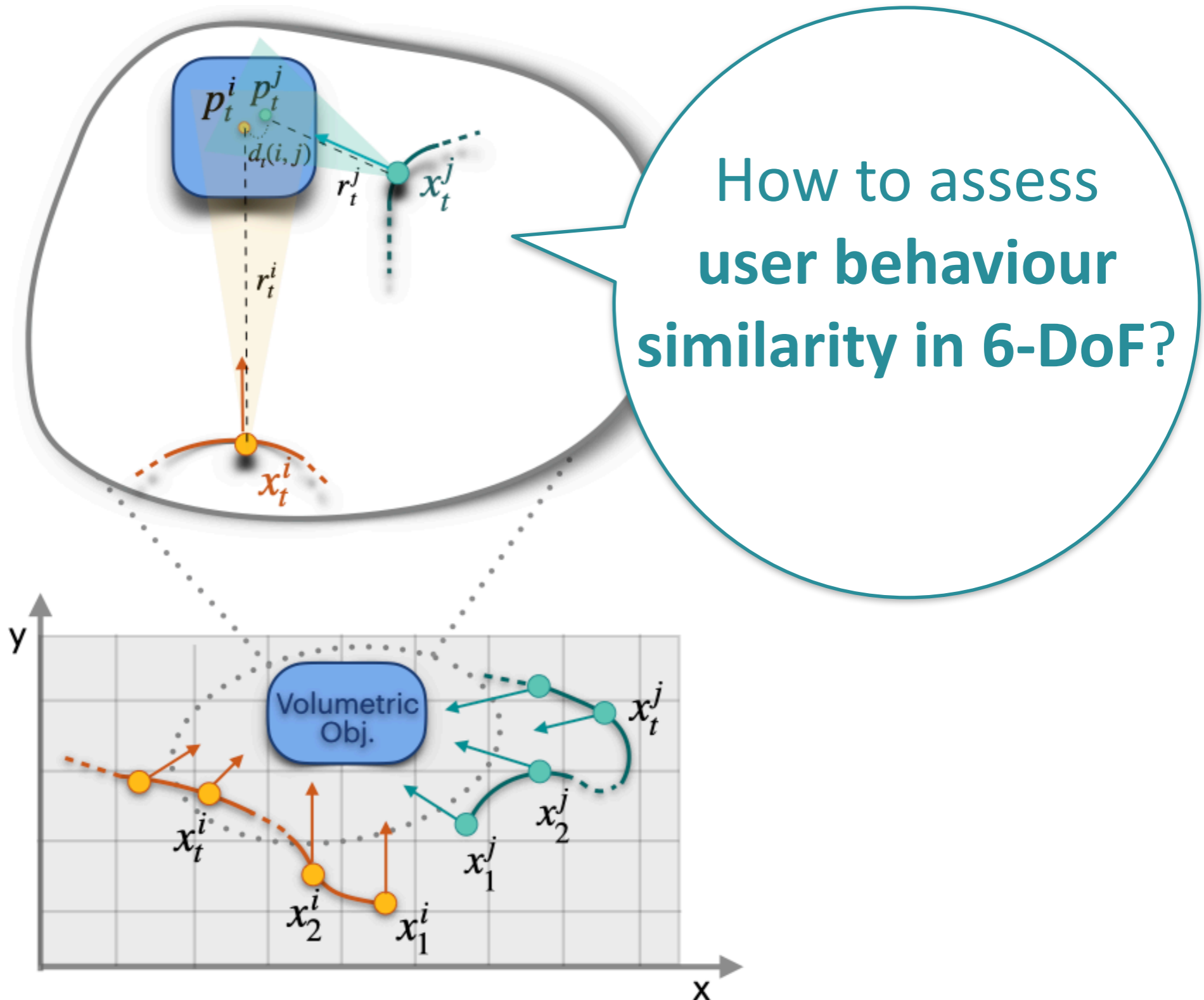
- Users are represented as an unweighted and undirected graph. Nodes are neighbours only if the geodesic distance between user viewport centres is lower than a given threshold.
- In graph theory, a clique is a set of nodes all connected each other.  
→ **clusters are maximal cliques** detected in the graph.





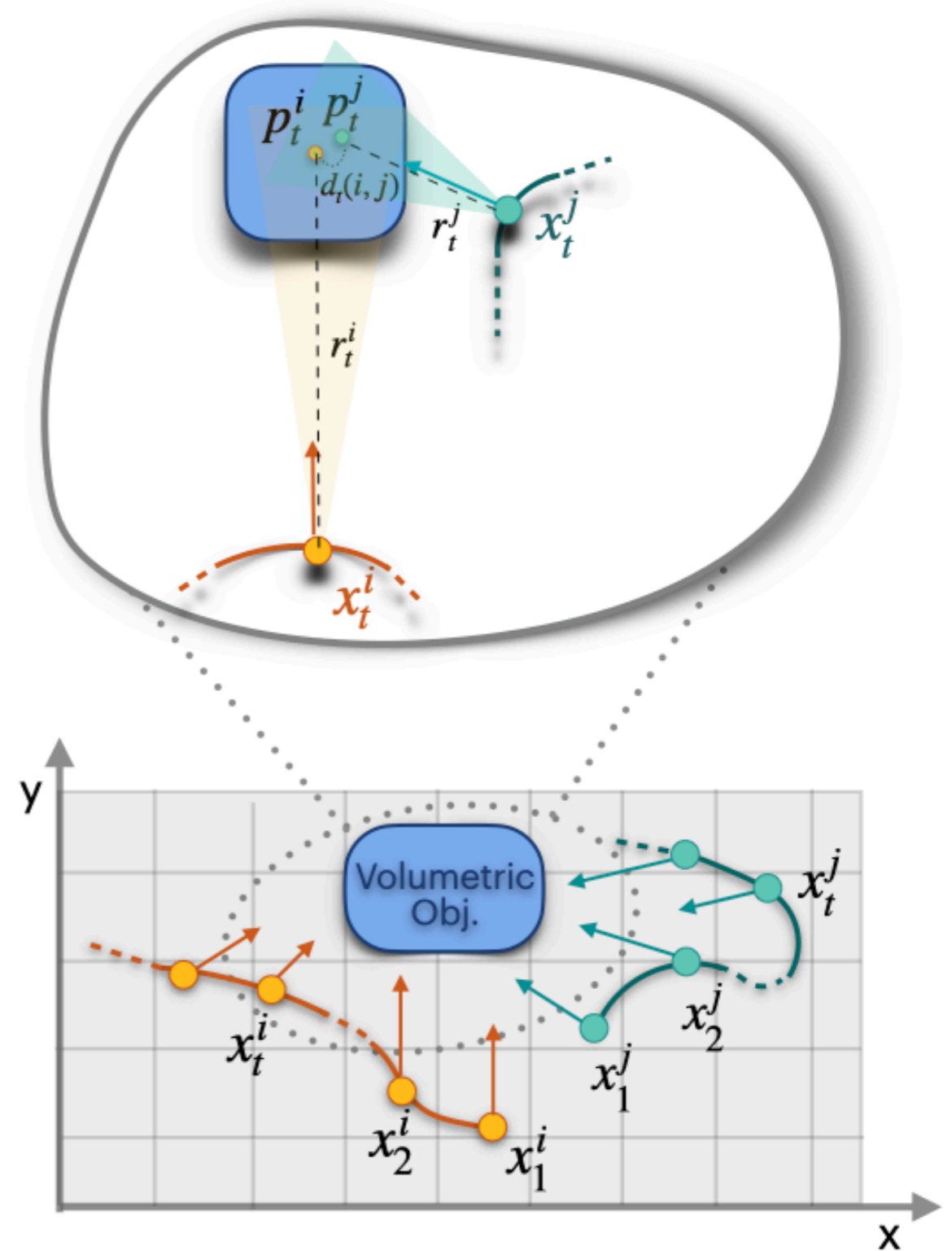
- Volumetric content (meshes or point clouds)
- The user has now the freedom to move inside the VR space: higher level of interactivity
- The media is displayed from an *outward* position

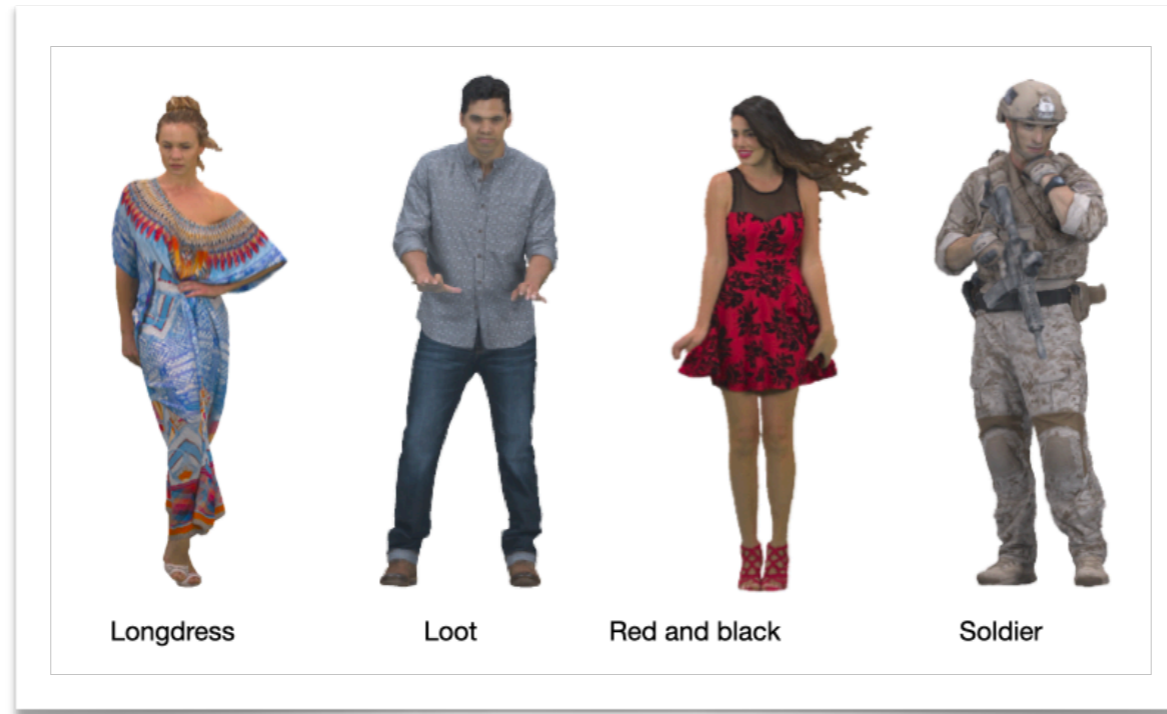
✗ The position of viewport center over time is not enough to identify user behaviour.



To verify if the **overlap ratio**  $O_t^{i,j}$  can be substituted with a distance between users, we consider 4 different **distance metrics**:

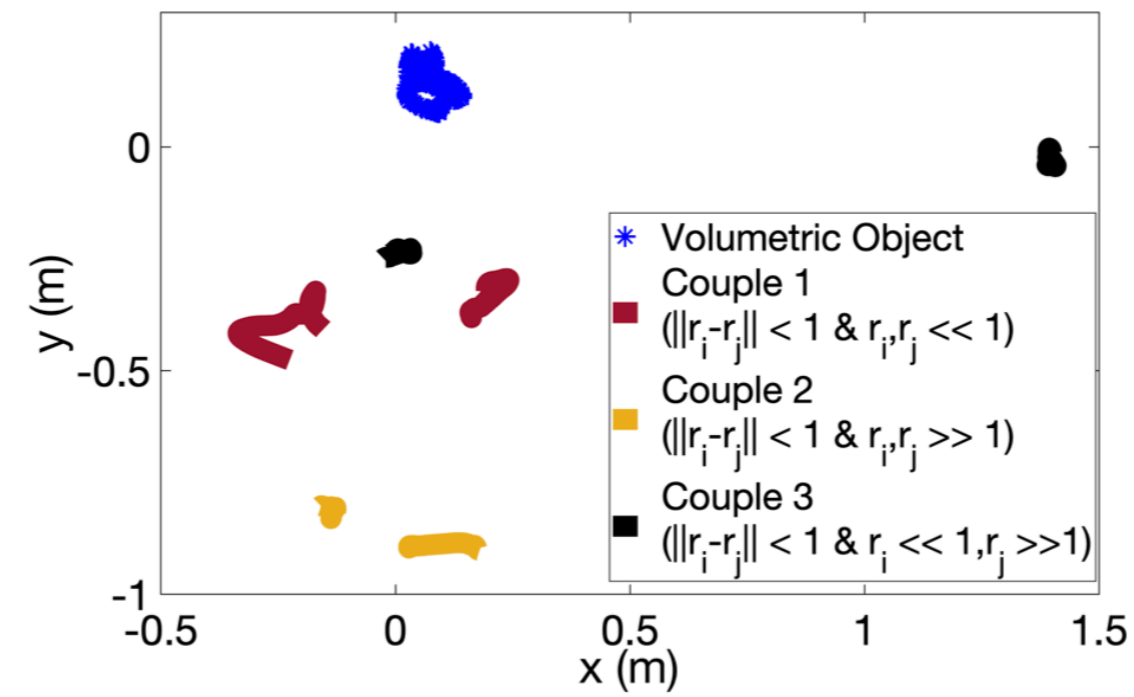
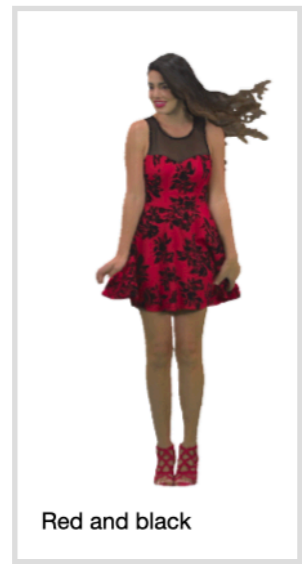
- $L_x^2 \rightarrow$  euclidean distance between  $x_t^i, x_t^j$  user positions in the space
- $L_p^2 \rightarrow$  euclidean distance between  $p_t^i, p_t^j$  viewport centres on PC
- $G_p \rightarrow$  geodesic distance between  $p_t^i, p_t^j$  viewport centres on PC
- $L_p^1 \rightarrow$  cityblock distance between  $p_t^i, p_t^j$  viewport centres on PC



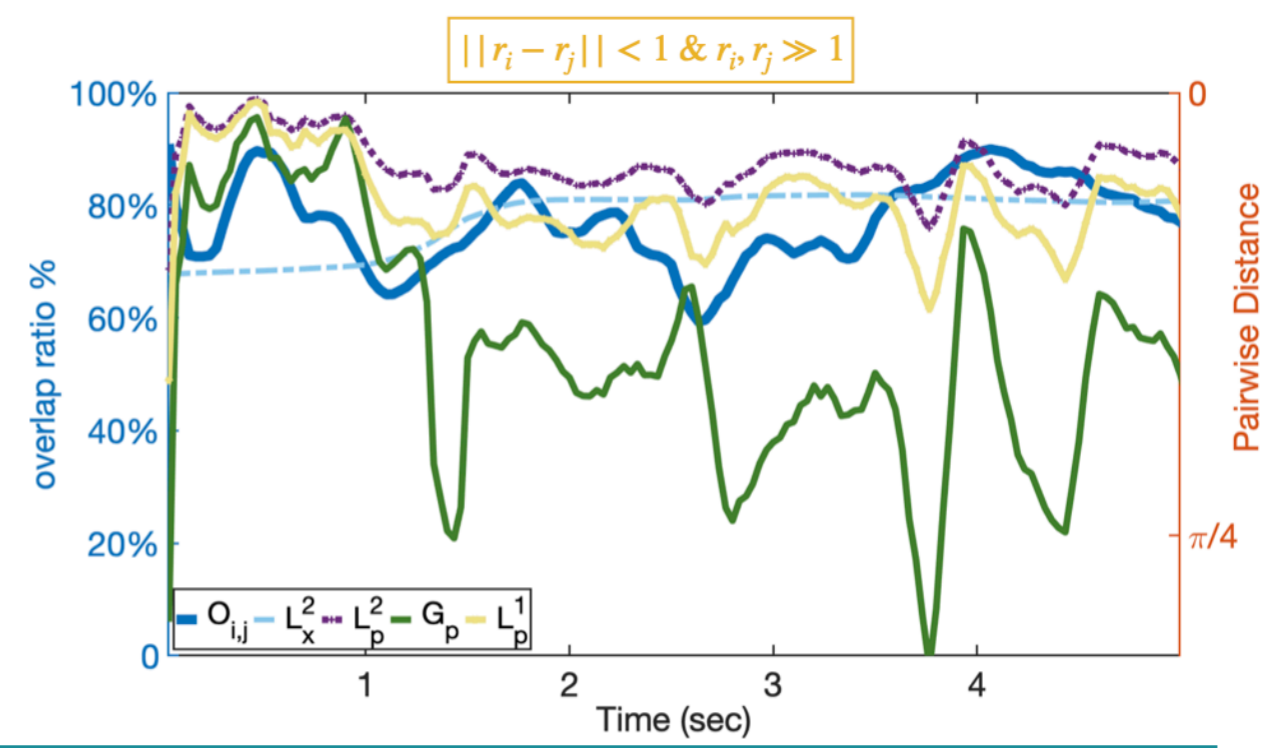
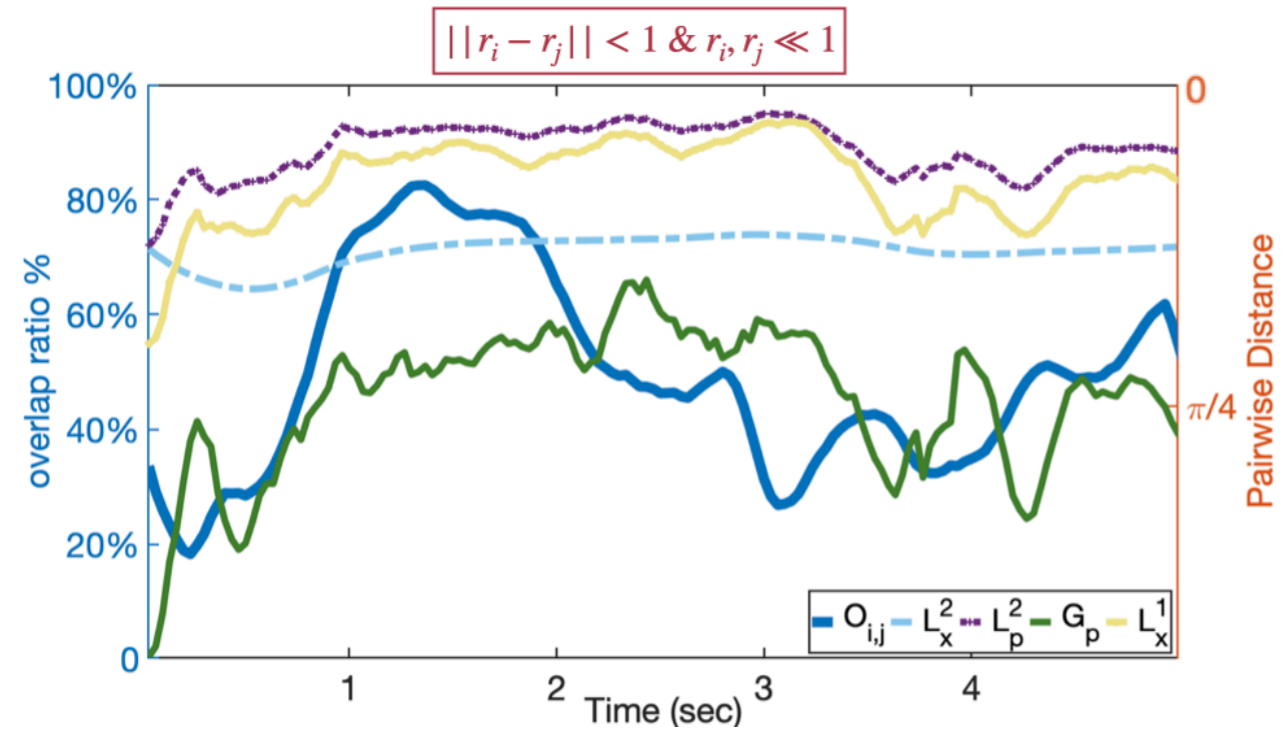


We based our investigations on a publicly available dataset of dynamic Point Clouds (PC) with collected navigation trajectories in 6-DoF [2].

# Distance as proxy for VP overlap?

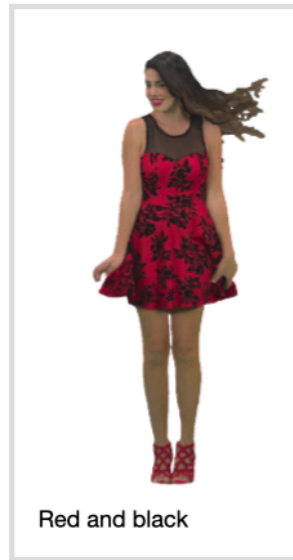


- $L_x^2$  → euclidean distance between  $x_t^i, x_t^j$  user positions in the space
- $L_p^2$  → euclidean distance between  $p_t^i, p_t^j$  viewport centres on PC
- $G_p$  → geodesic distance between  $p_t^i, p_t^j$  viewport centres on PC
- $L_p^1$  → cityblock distance between  $p_t^i, p_t^j$  viewport centres on PC

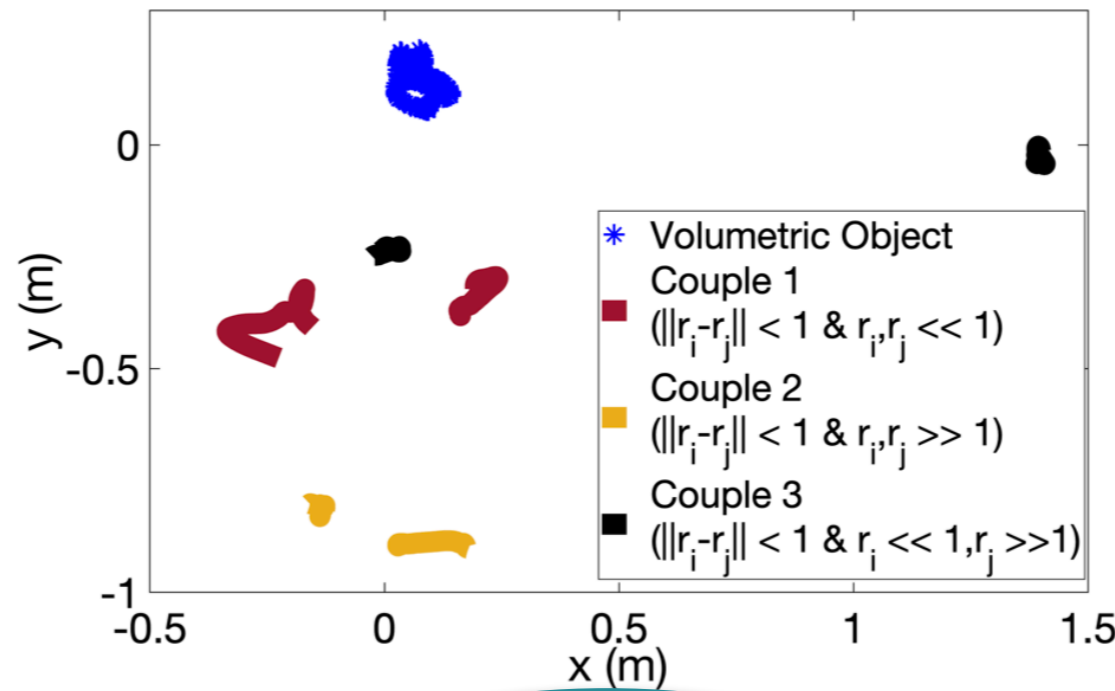




# Distance as proxy for VP overlap?



Red and black

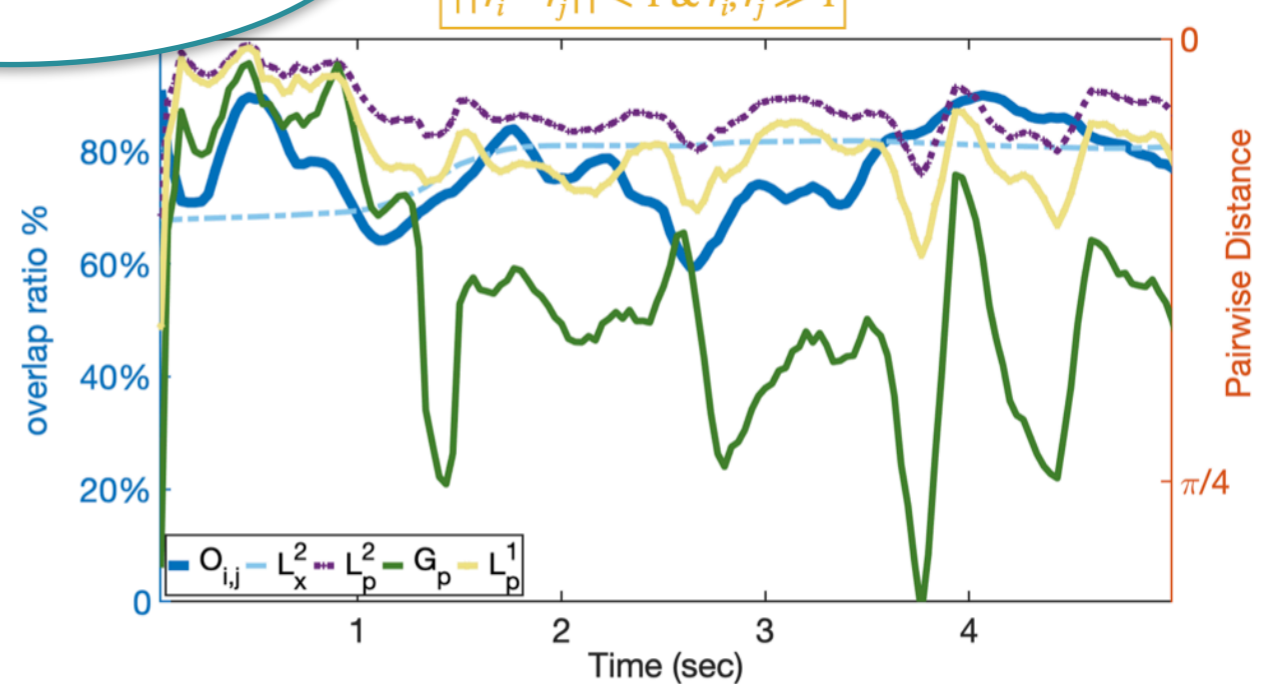
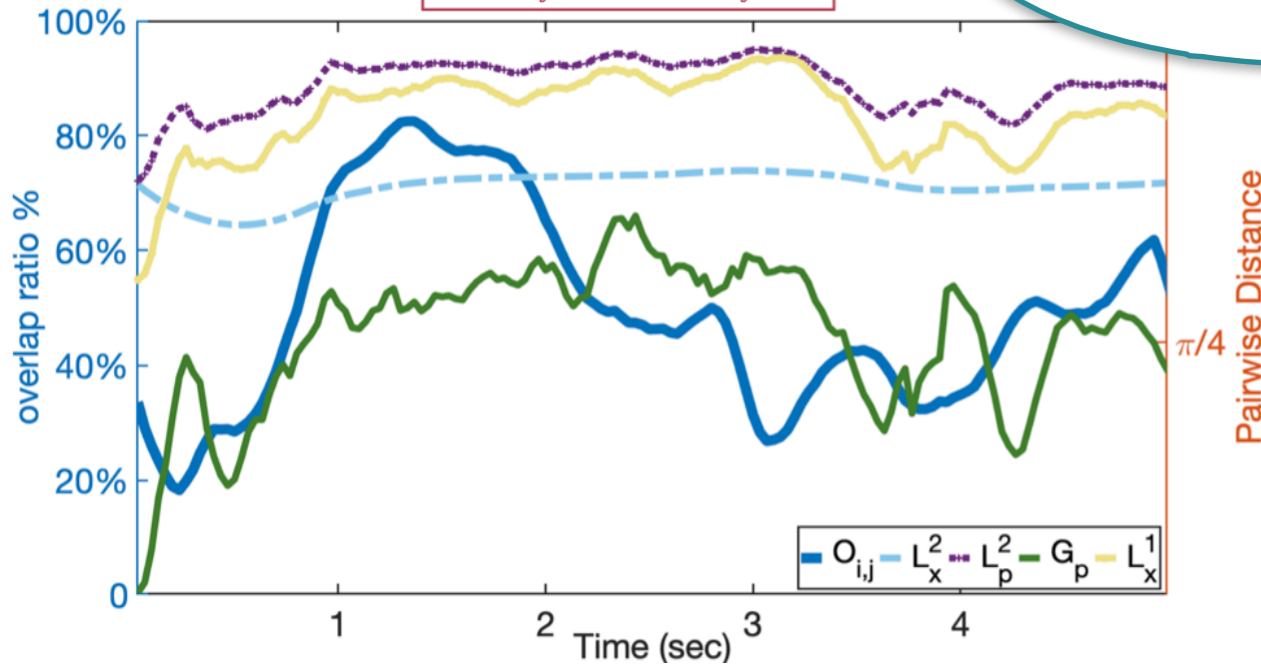


- $L_x^2$  → euclidean distance between  $x_t^i, x_t^j$  user positions in the space
- $L_p^2$  → euclidean distance between  $p_t^i, p_t^j$  viewport centres on PC
- $G_p$  → geodesic distance between  $p_t^i, p_t^j$  viewport centres on PC
- $L_p^1$  → cityblock distance between  $p_t^i, p_t^j$  viewport centres on PC

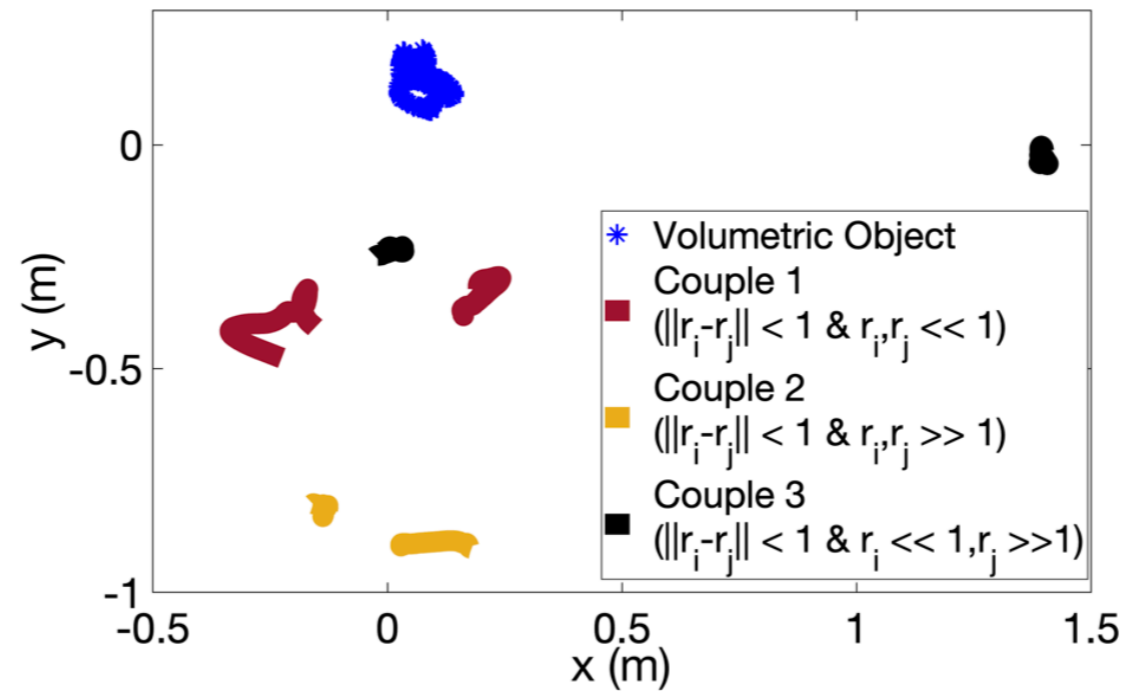
High overlap,  
low distance

$\|r_i - r_j\| < 1 \ \& \ r_i, r_j \ll 1$

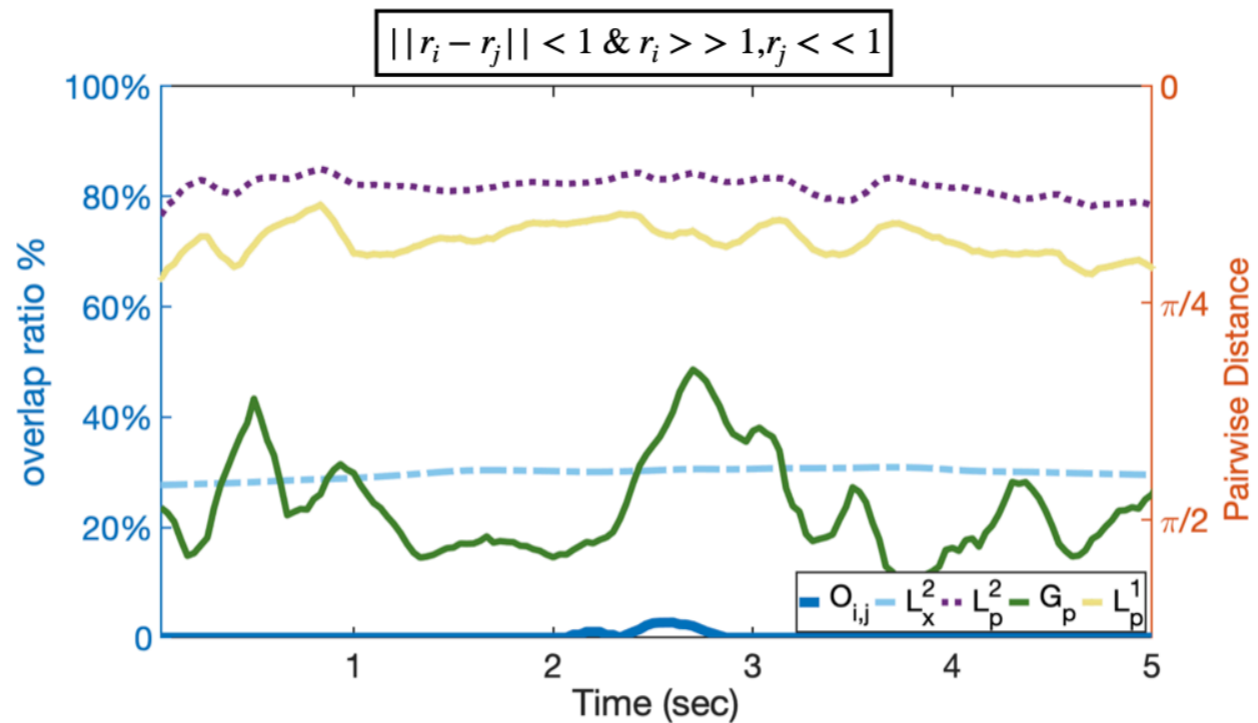
$\|r_i - r_j\| < 1 \ \& \ r_i, r_j \gg 1$



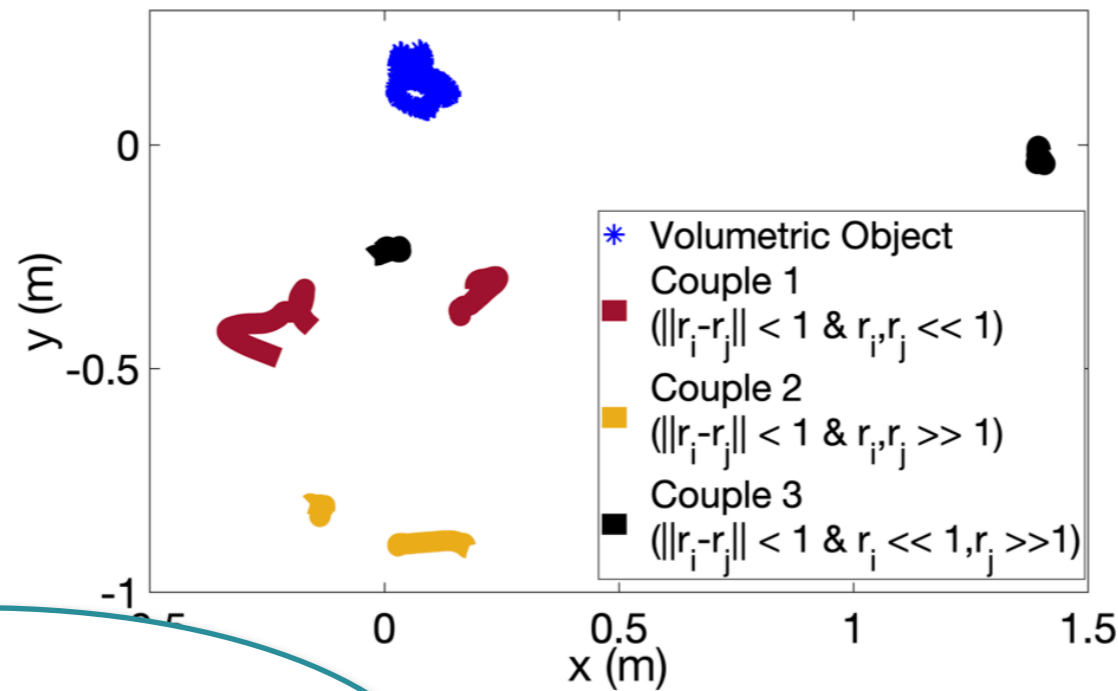
# Distance as proxy for VP overlap?



- $L_x^2$  → euclidean distance between  $x_t^i, x_t^j$  user positions in the space
- $L_p^2$  → euclidean distance between  $p_t^i, p_t^j$  viewport centres on PC
- $G_p$  → geodesic distance between  $p_t^i, p_t^j$  viewport centres on PC
- $L_p^1$  → cityblock distance between  $p_t^i, p_t^j$  viewport centres on PC

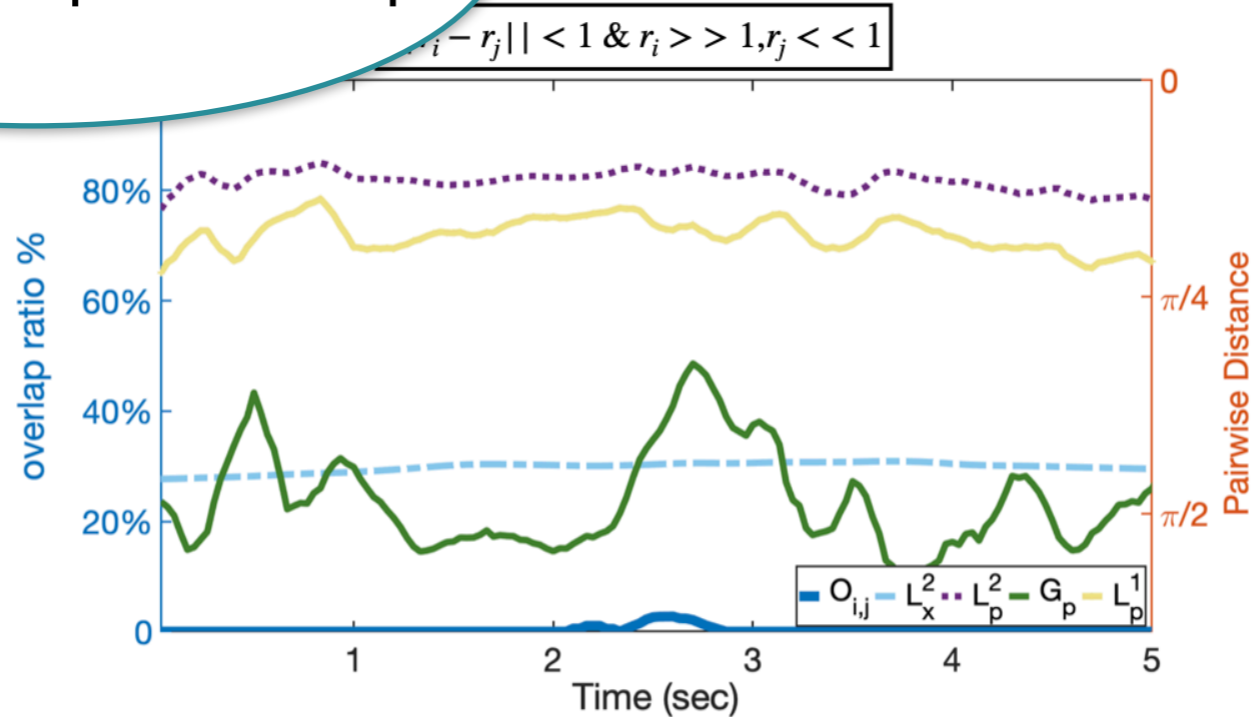


# Distance as proxy for VP overlap?



Distance metrics fail in capturing viewport overlap

- $L_x^2$  → euclidean distance between  $x_t^i, x_t^j$  user positions in the space
- $L_p^2$  → euclidean distance between  $p_t^i, p_t^j$  viewport centres on PC
- $G_p$  → geodesic distance between  $p_t^i, p_t^j$  viewport centres on PC
- $L_p^1$  → cityblock distance between  $p_t^i, p_t^j$  viewport centres on PC

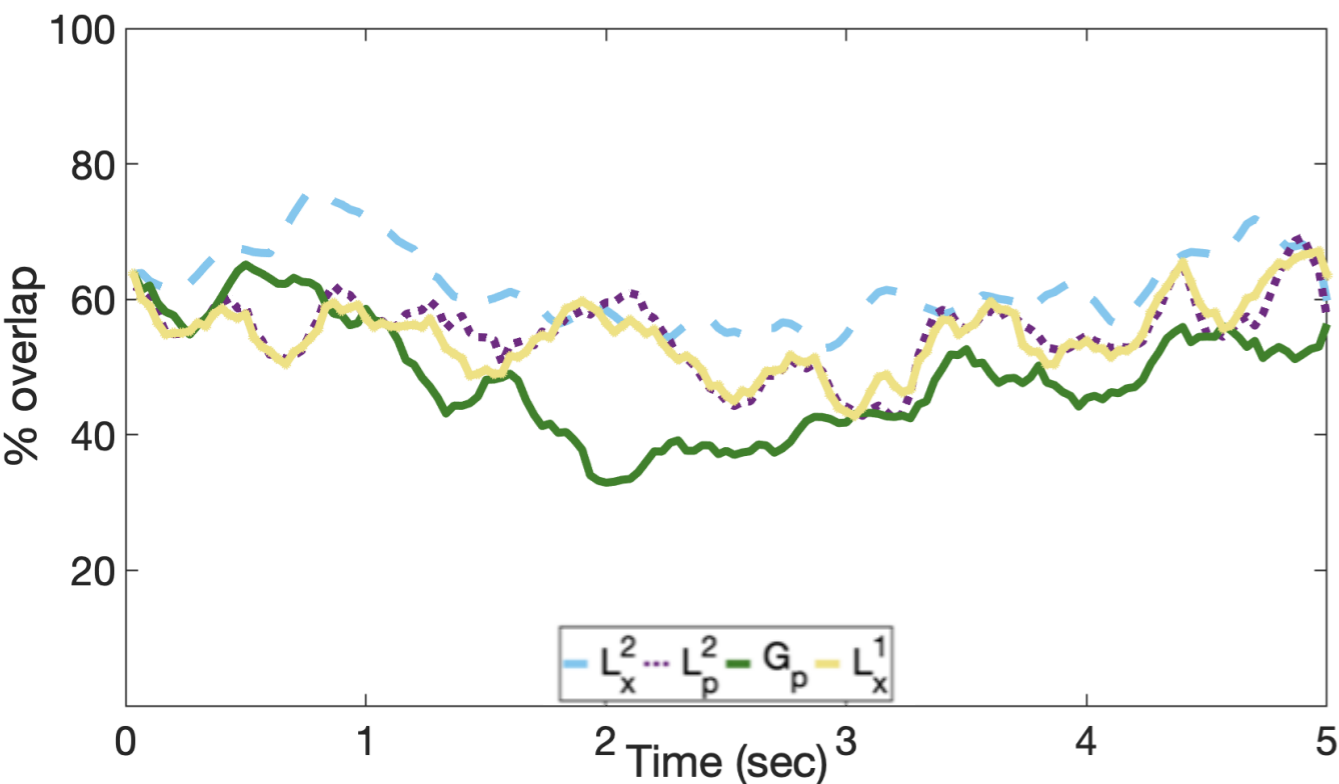


# Clustering results

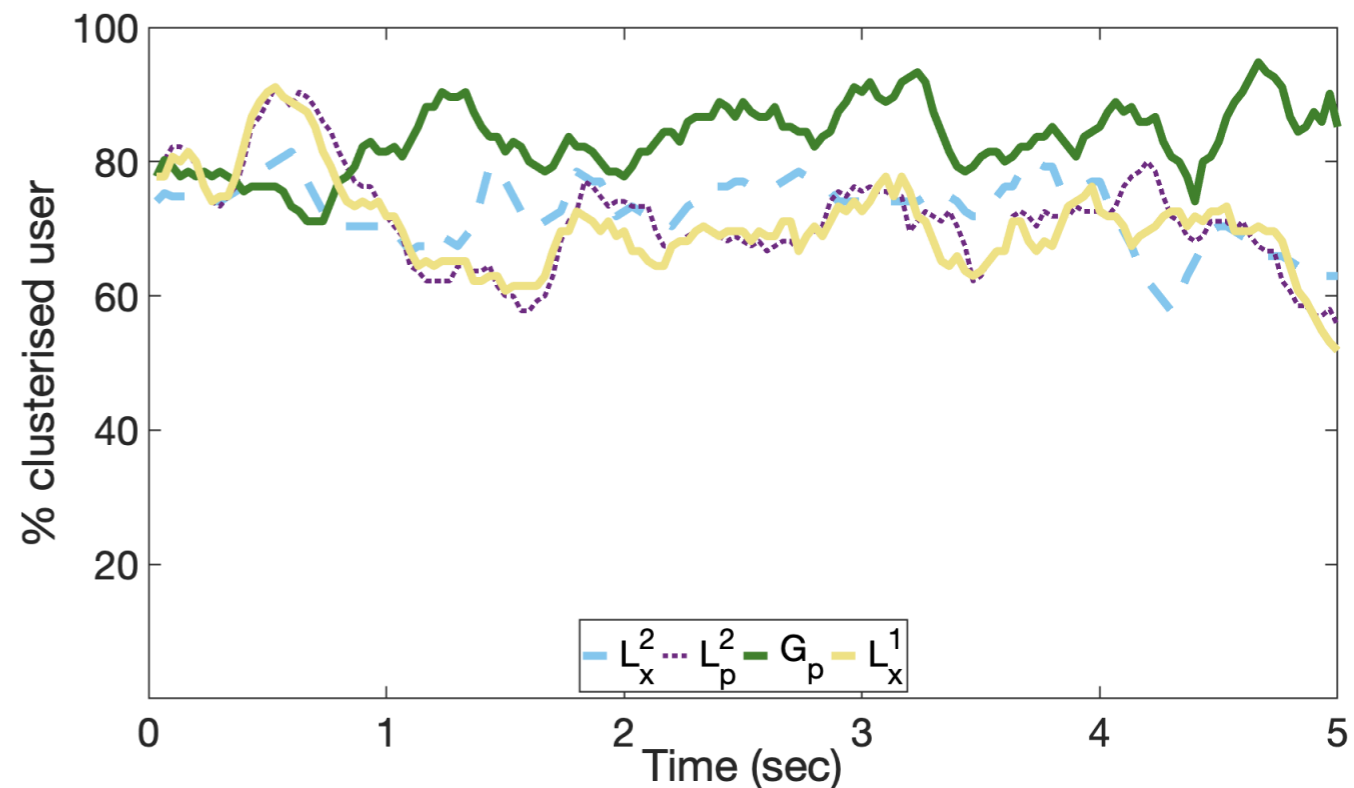


We now applied a **clique-based clustering** proposed in [1] to identify similar users that are attending the same portion of the omnidirectional content.

### Mean Overlap Over Time\*



### Mean N. Clustered Users Over Time\*

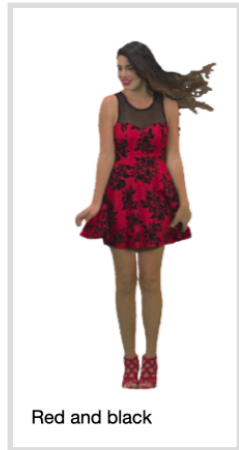


- $L_x^2$  → euclidean distance between  $x_t^i, x_t^j$  user positions in the space
- $L_p^2$  → euclidean distance between  $p_t^i, p_t^j$  viewport centres on PC

- $G_p$  → geodesic distance between  $p_t^i, p_t^j$  viewport centres on PC
- $L_p^1$  → cityblock distance between  $p_t^i, p_t^j$  viewport centres on PC

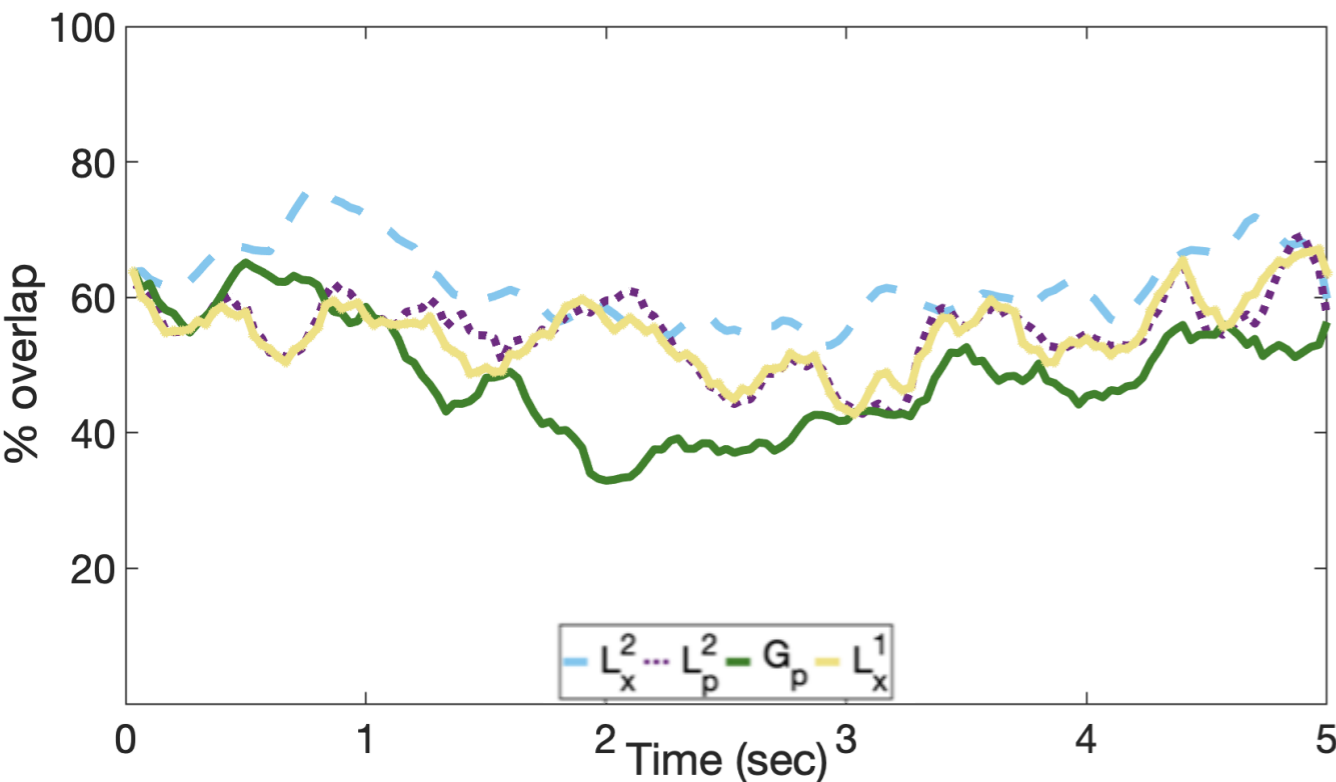
\* clusters > 2 users

# Clustering results

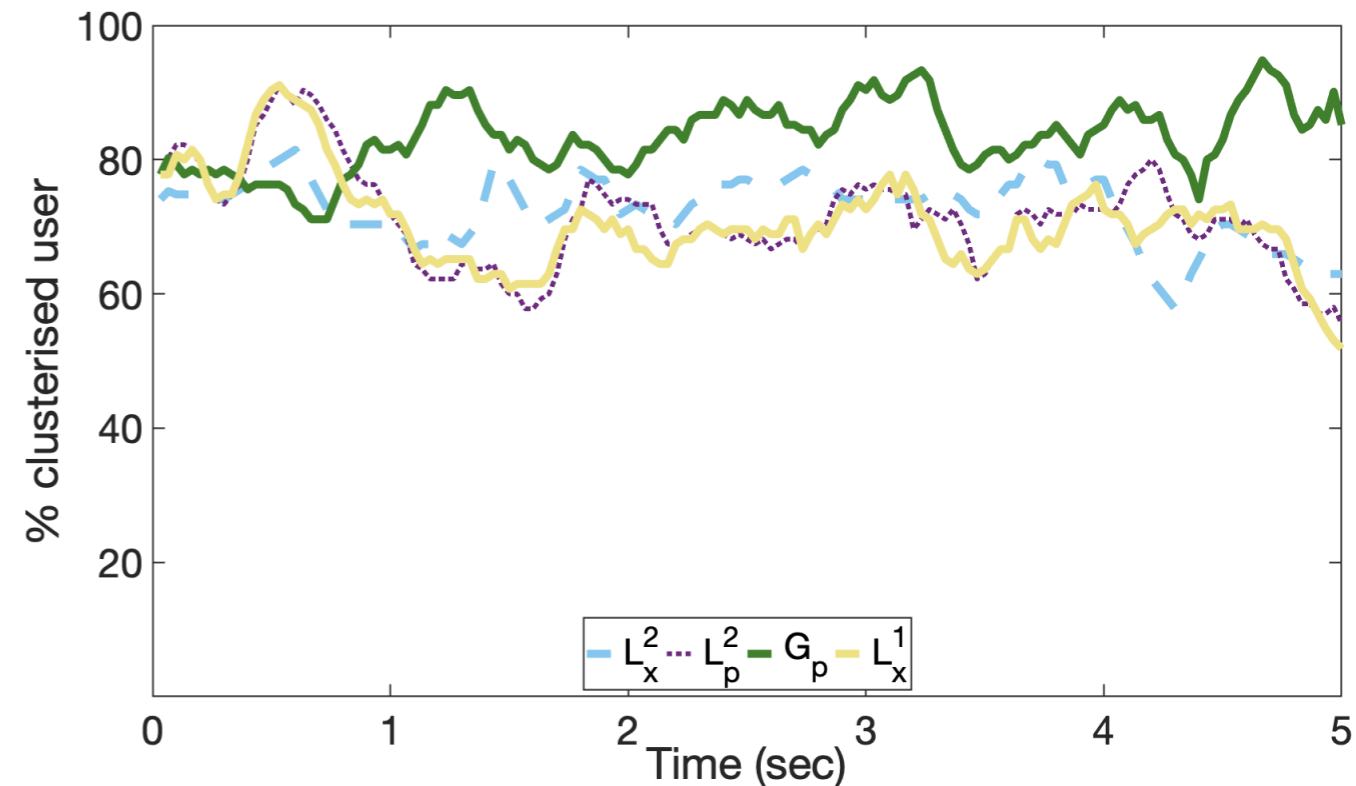


We now applied a **clique-based clustering** proposed in [1] to identify similar users that are attending the same portion of the omnidirectional content.

### Mean Overlap Over Time\*



### Mean N. Clustered Users Over Time\*



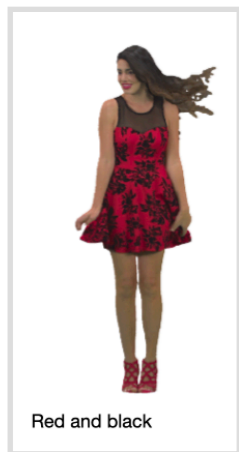
Clusters based on:

- $G_p$  → able to identify consistent groups of users
- $L_x^2$  → perform better in terms of viewport overlap

\* clusters > 2 users

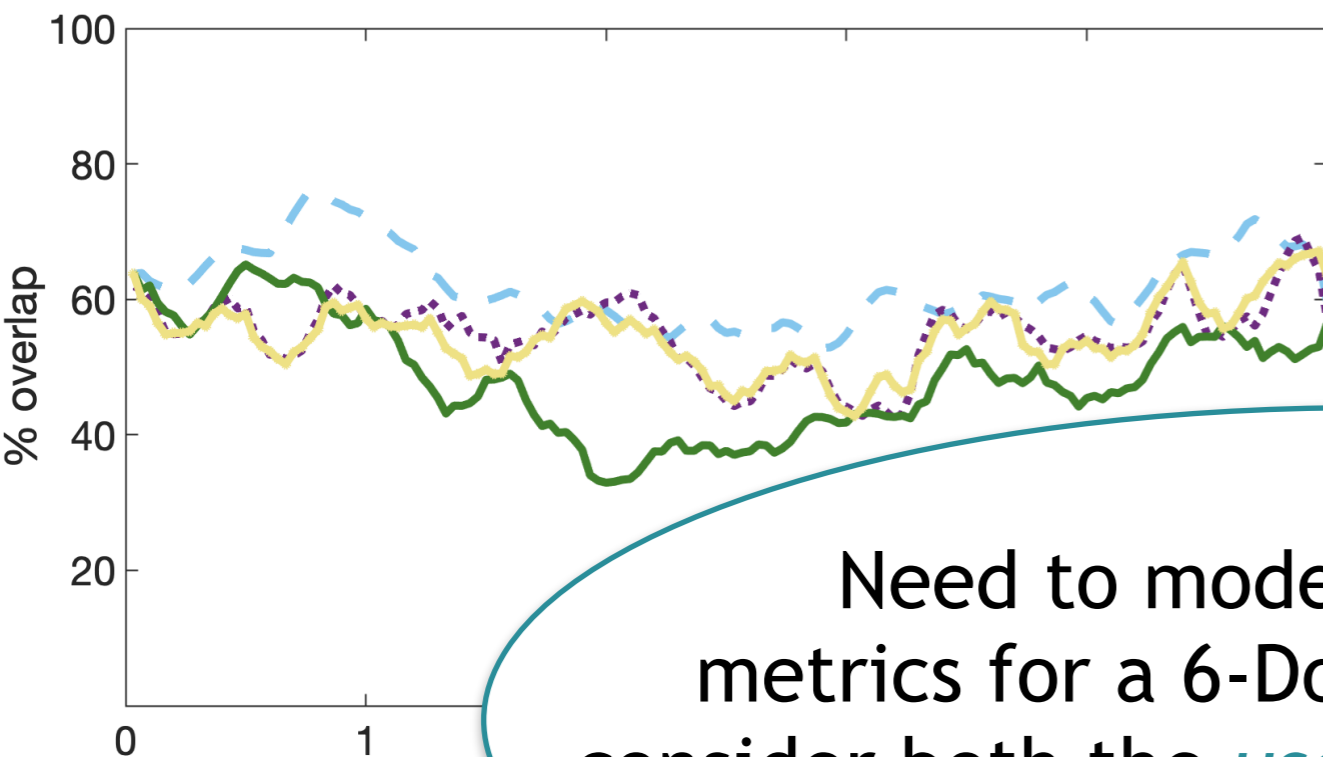


# Clustering results

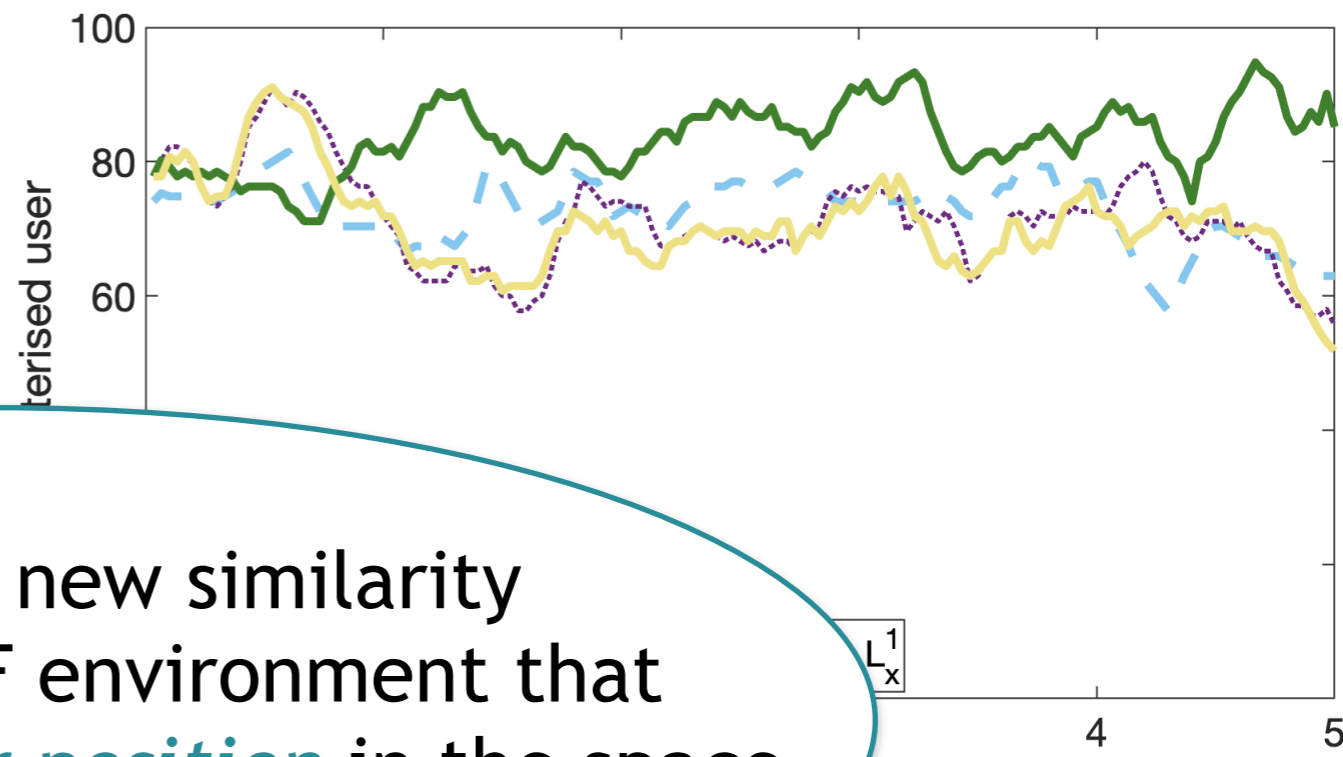


We now applied a **clique-based clustering** proposed in [1] to identify similar users that are attending the same portion of the omnidirectional content.

### Mean Overlap Over Time\*



### Mean N. Clustered Users Over Time\*



Need to model new similarity metrics for a 6-DoF environment that consider both the *user position* in the space and *viewing direction*.

$G_p$   $L_x^2$  → perform better in terms of viewport overlap

\* clusters > 2 users

[1] S. Rossi, F. De Simone, P. Frossard, and L. Toni. 2019. Spherical Clustering of Users Navigating 360° Content. In IEEE International Conference on Acoustics, Speech and Signal Processing. 24

We have shown key differences of interactivity in 3- and 6-DoF VR space:

- The definition of navigation trajectory is different
  - Current metrics fail in capturing similarity among users
- ➔ We are currently working on metrics that better model the user behaviour in 6-DoF and exploring different datasets.

**Thank you  
for your attention**

Questions?

---