Quantify VMAF Model Uncertainty Variability Using Bootstrapping

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VMAF framework



Bootstrapping - "Resampling with Replacement"

import numpy as np	
<pre>pop_size = 100000 sample_size = 1000 trials = 100</pre>	
<pre>pop_mean = 5 pop_std = 11 population = np.random.randn(pop_size) * pop_std + pop_mean sample = population[:sample_size]</pre>	
<pre>means_pop = [np.mean(np.random.choice(population, size=sample_size, replace=True)) for _ in range(trials)] means_bootstrap = [np.mean(np.random.choice(sample, size=sample_size, replace=True)) for _ in range(trials)]</pre>	
<pre>stds_pop = [np.std(np.random.choice(population, size=sample_size, replace=True)) for _ in range(trials)] stds_bootstrap = [np.std(np.random.choice(sample, size=sample_size, replace=True)) for _ in range(trials)]</pre>	
<pre>print('std of sample mean: {} (ground truth)'.format(np.std(means_pop))) print('std of sample mean: {} (bootstrapped)\n'.format(np.std(means_bootstrap)))</pre>	
<pre>print('std of sample std: {} (ground truth)'.format(np.std(stds_pop))) print('std of sample std: {} (bootstrapped)\n'.format(np.std(stds_bootstrap)))</pre>	<pre>std of sample mean: 0.310599353041 (ground truth) std of sample mean: 0.3649194485 (bootstrapped)</pre>
<pre>print('Done.')</pre>	ctd of comple ctd, 0 221722205624 (around truth)
	std of sample std: 0.231725205054 (ground truth) std of sample std: 0.238048033854 (bootstrapped)
B. Efron, "Bootstrap Methods: Another Look at the Jackknife", The Annals of Statistics, 1979, Vol. 7, No. 1, 1 - 26	Done.

Bootstrapping in Regression Models: Observation (Top) vs. Residue (Bottom)



P. Hall, "On Bootstrap confidence intervals in nonparametric regression", The Annals of Statistics, 1992, Vol. 20, No. 2, 695 - 711

Result: NFLX Public Dataset



Result: LIVE Mobile Dataset



Result: Impact of Number of Models



*95% C.I., Bootstrapping on observations

Observations

- VMAF v0.6.1 has tighter confidence interval on the high-score range compared to the low-score range
- Bootstrapping on the residues can yield tighter confidence interval than bootstrapping on the observations themselves most of the time (occasionally it can be the other way around)
- The estimated confidence interval is quite robust against the number of models used in bootstrapping

VMAF framework



Open questions

- How to combine the two variabilities?
- How to make the trade-off?



Coming up next to VMAF open-source repo

- Release of new 4K model (Monday's talk)
- Confidence interval of VMAF model (this talk)
- Enhanced temporal features
- New HDR model

Backup Slides



Result: LIVE Video Dataset



Result: VQEGHD3 Dataset

